On Bayesian Estimation in Generalized Geometric Series Distribution

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Abstract: In this study, a Bayesian analysis of Generalized Geometric Series Distribution (GGSD) under different types of loss functions have been studied.

Key words: Squared error loss function, Bayes estimator, beta distribution, GGSD, binomial distribution, India

INTRODUCTION

The probability function of Generalized Geometric Series Distribution (GGSD) was given by Mishra (1982) by using the results of the lattice path analysis as:

$$P(X=x) = \frac{1}{1+\beta x} \left( 1+\beta x \right)^x \theta^x (1-\theta)^{x-1}$$

$$x = 0, 1, 2, \ldots, 0 < \theta < 1$$

(1)

It can be seen that at $\beta = 1$, Eq. 1 reduced to simple geometric distribution and is a particular case of Jain and Consul (1971)'s generalized negative binomial distribution in the same way as the geometric distribution is a particular case of the negative binomial distribution.

The various properties and estimation of Eq. 1 have been discussed by Mishra (1982), Mishra and Singh (1982). Hassan et al. (2007) discussed the Bayesian analysis under non-informative and conjugate priors. In this study, the Bayesian analysis of Generalized Geometric Series Distribution (GGSD) under different symmetric loss functions have been studied.

Preliminary theory: Let $x$ be a random variable whose distribution depends on $r$ parameters $\theta_1, \theta_2, \ldots, \theta_r$, and let $\Omega$ denotes the parameter space of possible values of $\theta$. For the general problem of estimating some specified real-valued function $\phi(\theta)$ of the unknown parameters $\theta$ from the results of a random sample of $n$ observations, we shall assume that $\phi(\theta)$ is defined for all $\theta$ in $\Omega$.

Let $x_1, x_2, \ldots, x_n$ be the sample observations. Also, let $\hat{\theta}$ be an estimate of $\phi(\theta)$ and let $L_i(\theta, \hat{\theta})$ be the loss incurred by taking the value of $\phi(\theta) = \hat{\theta}$. It should be noted that we are restricting consideration hereto loss functions which depend on $\theta$ through $\phi(\theta)$ only. If $\Psi(\theta)$ is the prior density of $\theta$ then according to Bayes' theorem the posterior density of $\theta$ is

$$l(\theta|x) \psi(\theta)/p(x)$$

where $l(\theta|x)$ is the likelihood function of $\theta$ given the sample $x$ and

$$p(x) = \int l(\theta|x) \psi(\theta) d\theta$$

It follows that for a given $x$, the expected loss i.e., risk of the estimator $\hat{\theta}$ is:

$$R(\hat{\theta}(x), \phi(\theta)) = \int L(\hat{\theta}(x), \phi(\theta)) \frac{l(\theta|x) \psi(\theta)}{p(x)} d\theta$$

(2)

Assuming the existence of Eq. 2 and the sufficient regularity conditions prevail to permit differentiation under the integral sign, the optimum estimator $\hat{\theta}(x)$ of $\Phi(\theta)$ will be a solution of the equation:

$$\int \frac{dL_i(\theta, \hat{\theta})}{d\theta} \psi(\theta) d\theta = 0$$

(3)

The validity of Eq. 3 and the desirability that it should lead to a unique solution necessarily impose restrictions of one's choice of loss function and prior density of $\theta$. The loss functions which have been considered here are as follows:

$$L_1(\hat{\theta}, \theta) = c(\hat{\theta} - \theta)^2$$

$$L_2(\hat{\theta}, \theta) = c(\hat{\theta} - \theta)^2$$

$$L_3(\hat{\theta}, \theta) = c(\sqrt{\theta} - \sqrt{\hat{\theta}})^2$$

$$L_4(\hat{\theta}, \theta) = c\left(\frac{\sqrt{\theta} - \sqrt{\hat{\theta}}}{\theta}\right)^2$$
Let \( L_1(\tilde{\theta}, \theta) = \begin{cases} 0 \text{ if } |\tilde{\theta} - \theta| < \delta \\ 1 \text{ otherwise} \end{cases} \)

Where \( \delta \) is a small known quantity:

\[
L_2(\tilde{\theta}, \theta) = \begin{cases} 0 \text{ if } \delta_1 < |\tilde{\theta} - \theta| < \delta_2 \\ 1 \text{ if } \tilde{\theta} - \theta < \delta_1 \\ 1 \text{ if } \tilde{\theta} - \theta > \delta_2 \end{cases}
\]

Where \( \delta_1 \) and \( \delta_2 \) are two known quantities.

**MATERIALS AND METHODS**

Bayesian estimation of parameter \( \theta \) of GGSD under different priors: The likelihood function from Eq. 1 is obtained as:

\[
L(x / \theta, \beta) = \prod_{i=1}^{n} \left( \frac{1}{1 + \beta x_i} \right)^{1 + \beta x_i} \theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i} \]

\[
= k \theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i} \]

Where:

\[
k = \frac{1}{\sum_{i=1}^{n} \frac{1}{1 + \beta x_i} (1 + \beta x_i) x_i} \quad \text{and} \quad y = \sum_{i=1}^{n} x_i
\]

When \( \beta \) is known, the part of the likelihood function which is relevant to Bayesian inference on the unknown parameter \( \theta \) is \( \theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i} \).

Bayesian estimation of parameter \( \theta \) of GGSD under non-informative prior: We assume prior of \( \theta \) as:

\[
g(\theta) = \frac{1}{\theta}, \quad 0 < \theta < 1
\]

The posterior distribution of \( \theta \) from Eq. 4 and 5 is:

\[
\prod(\theta / y) = \frac{L(x / \theta, \beta)g(\theta)}{\int L(x / \theta, \beta)g(\theta)d\theta} = \frac{\theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i}}{B(y, n + \beta y - y + 1)}\quad (6)
\]

The Bayes estimator of parametric function \( \phi(\theta) \) under squared error loss function is the posterior mean which is given as:

\[
\hat{\theta}(\theta) = \frac{1}{\int \phi(\theta) \theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i} d\theta} B(y, n + \beta y - y + 1)
\]

If we take \( \phi(\theta) = 0 \), the Bayes estimate of \( \theta \) is given by:

\[
\hat{\theta} = \frac{1}{B(y, n + \beta y - y + 1)} \int \phi(\theta) \theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i} d\theta
\]

(7)

This coincides with the moment and ML estimate of \( \theta \).

Bayesian estimation of parameter \( \theta \) of GGSD under beta prior: The more general Bayes estimator of \( \theta \) can be obtained by assuming the beta distribution as prior information of \( \theta \). Thus:

\[
g(\theta; a, b) = \frac{\theta^{a-1} (1 - \theta)^{b-1}}{B(a, b)} \quad a, b > 0, \quad 0 < \theta < 1 \quad (8)
\]

The posterior distribution of \( \theta \) is defined as:

\[
\pi(\theta | y) = \frac{\theta^{a+y-1} (1 - \theta)^{b+y-1}}{\int_0^1 \theta^{a+y-1} (1 - \theta)^{b+y-1} d\theta} = \frac{\theta^{a+y-1} (1 - \theta)^{b+y-1}}{B(y + a, n + \beta y - y + b)}\quad (9)
\]

The Bayes estimator of parametric function \( \phi(\theta) \) under squared error loss function is the posterior mean and is given as:

\[
\hat{\theta} = \int_0^1 \phi(\theta) \theta^{a+y-1} (1 - \theta)^{b+y-1} d\theta = \frac{a + y}{B(y + a, n + \beta y - y + b)}\quad (10)
\]

If we take \( \phi(\theta) = 0 \) then Bayes estimator of \( \theta \) is given as:

\[
\hat{\theta} = \frac{a + y}{n + a + b + \beta y}\quad (11)
\]

If \( a = b = 0 \), Eq. 11 coincides with Eq. 7. We can consider the more generalized prior as:

\[
L(\tilde{\theta}, \theta) = \phi(\tilde{\theta}) (\theta^{a+y-1} - \theta^{n+y-1})\quad (12)
\]
Where \( c \) is a positive constant, \( a \) and \( b \) are known quantities. Under the above loss function, the Bayes’ estimator \( \hat{\theta} \) is given by:

\[
\hat{\theta} = \left[ \frac{E_0(\theta^* | x)}{E_0(\theta | x)} \right]^{\gamma/b}
\]

Where:

\[
E_0(\theta^* | x) = \int_{\theta} \theta^* P(\theta | x) d\theta
\]

\[
= \frac{1}{\beta(y,n + \beta y - y + 1)} \int_{\theta} \theta^{n + \beta y - y} (1 - \theta)^{\beta y - y + 1} d\theta
\]

\[
= \frac{\Gamma(y + a)\Gamma(n + \beta y + 1)}{\Gamma(y)\Gamma(n + \beta y + a + 1)}
\]

(13)

and:

\[
E_0(\theta^* | x) = \int_{\theta} \theta^* P(\theta | x) d\theta
\]

\[
= \frac{1}{\beta(y,n + \beta y - y + 1)} \int_{\theta} \theta^{n + \beta y - y} (1 - \theta)^{\beta y - y + 1} d\theta
\]

\[
= \frac{\Gamma(y + a + b)\Gamma(n + \beta y + a + 1)}{\Gamma(y + a)\Gamma(n + \beta y + a + b + 1)}
\]

(14)

Using Eq. 11, 13 and 14 the Bayes’ estimator \( \hat{\theta} \) under the loss function Eq. 12 is given by:

\[
\hat{\theta} = \left[ \frac{\Gamma(y + a + b)\Gamma(n + \beta y + a + 1)}{\Gamma(y + a)\Gamma(n + \beta y + a + b + 1)} \right]^{\gamma/b}
\]

(15)

- Substituting \( a = 0 \) and \( b = 1 \), the loss function Eq. 12 becomes the loss function \( L_1 \) and the Bayes’ estimator under the loss function \( L_1 \) using Eq. 15 is:

\[
\hat{\theta}_1 = \frac{y}{n + \beta y + 1}
\]

Which is the mean of the posterior distribution.

- Substituting \( a = -2 \) and \( b = 1 \), the loss function Eq. 12 becomes the loss function \( L_2 \) and the Bayes’ estimator under the loss function \( L_2 \) using Eq. 15 is (Table 1):

\[
\hat{\theta}_2 = \frac{y - 2}{n + \beta y - 1}
\]

Table 1: Shows the seven different loss functions and the respective Bayes’ estimators of \( \theta \) under those loss functions

<table>
<thead>
<tr>
<th>Loss function</th>
<th>Bayes’ estimator of the parameter</th>
</tr>
</thead>
<tbody>
<tr>
<td>( L_1(\hat{\theta}, \theta) = c(\hat{\theta} - \theta)^2 )</td>
<td>( \hat{\theta}_1 = \frac{y}{n + \beta y + 1} )</td>
</tr>
<tr>
<td>( L_2(\hat{\theta}, \theta) = c(\hat{\theta} - \theta)^2 )</td>
<td>( \hat{\theta}_2 = \frac{y - 2}{n + \beta y - 1} )</td>
</tr>
<tr>
<td>( L_3(\hat{\theta}, \theta) = c\sqrt{\hat{\theta} - \theta} )</td>
<td>( \hat{\theta}_3 = \left[ \frac{\Gamma(y + 1/2)\Gamma(n + \beta y + 1)}{\Gamma(y)\Gamma(n + \beta y + 3/2)} \right]^{2} )</td>
</tr>
<tr>
<td>( L_4(\hat{\theta}, \theta) = c\sqrt{\hat{\theta} - \theta} )</td>
<td>( \hat{\theta}_4 = \left[ \frac{\Gamma(y - 1/2)\Gamma(n + \beta y)}{\Gamma(y - 1)\Gamma(n + \beta y + 1/2)} \right]^{2} )</td>
</tr>
<tr>
<td>( L_5(\hat{\theta}, \theta) = \frac{0 \text{ if }</td>
<td>\hat{\theta} - \theta</td>
</tr>
</tbody>
</table>

Where \( \delta \) is a small known quantity:

- Substituting \( a = 0 \) and \( b = 1.2 \), the loss function Eq. 12 becomes the loss function \( L_1 \) and the Bayes’ estimator under the loss function \( L_1 \) using Eq. 15 is:

\[
\hat{\theta}_1 = \left[ \frac{\Gamma(y + 1/2)\Gamma(n + \beta y + 1)}{\Gamma(y)\Gamma(n + \beta y + 3/2)} \right]^{2}
\]

- Substituting \( a = 0 \) and \( b = 1.2 \), the loss function Eq. 12 becomes the loss function \( L_4 \) and the Bayes’ estimator under the loss function \( L_4 \) using Eq. 15 is:

\[
\hat{\theta}_4 = \left[ \frac{\Gamma(y - 1/2)\Gamma(n + \beta y)}{\Gamma(y - 1)\Gamma(n + \beta y + 1/2)} \right]^{2}
\]

- The Bayes’ estimator for the zero-one type of loss function \( L_6 \) under is the mode of the posterior distribution as:

\[
\hat{\theta}_6 = \frac{y - 1}{n + \beta y - 1}
\]

- The Bayes’ estimator for the special zero-one type of loss function \( L_7 \) is:
\[ \hat{\theta}_0 = \frac{y - 1}{n + \beta y - 1} + \frac{\hat{\delta}_1 \hat{\delta}_2}{2} \]

RESULTS AND DISCUSSION

As \( \delta_1 = -\delta_1 \), the Bayes’ estimators \( \hat{\delta}_1 \) and \( \hat{\delta}_2 \) are identical. It has been also noted that as \( \beta = 1 \), the above estimators are the Bayesian estimators of the parameter of simple geometric distribution under the above loss functions \( L_1, L_2, L_3, L_4, L_5 \) and \( L_6 \), respectively.

REFERENCES