

Learning Method of WeDo+Scratch based on Programming for Non-Programing Major

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Abstract: For boosting computational thinking skills, the need of SW education has been becoming conspicuous recently and algorithm-based programming education has been conducted. However, new learners, who have never learned programming before, find difficulties understanding the basic syntax and the logic of computer languages in the process of acquiring programming techniques and also find difficulties making out algorithm and converting it into computer language code. These difficulties are due to limited time for acquisition of the techniques. In this study, an education method to draw interest from new learners into programming and develop algorithm thinking skills using the basic syntax of programming and to develop abilities to solve problems that arise in programming shall be introduced. This education makes the concept of SW education easier to approach by interlocking the concept of WeDo constructionism-based robotics built with LEGO Model blocks and scratch-based programming of more effective programming education method to learn and use the basic programming concept through prerequisite.

Key words: LEGO WeDo, scratch, robotics, constructionism, programming education

INTRODUCTION

The algorithm and programming education for improving abilities to solve problems based on SW has been conducted recently for boosting computational thinking skills (Bae *et al.*, 2009). However, new learners who have never learned programming before, find difficulties understanding the basic syntax and the basic logic of computer languages in the process of acquiring program techniques. Also, there are times to acquire programming techniques. Therefore, there is a need of more effective programming education method to learn and use the basic programming concept through prerequisite fundamental learning in order to solve the difficulties learning the programming languages.

In this study, a fundamental learning method to develop abilities of new learners to have algorithm thinking skills using the basic syntax of programming and to solve many different problems made in the process of programming shall be introduced. The learning method proposed in this study allows more effective approach to the concept of programming as it makes learners have interests in basic programming by interlocking the robotics concept, built with LEGO Model blocks based on the

construction of WeDo with scratch-based programming. This study proposes the way of learning by creating and combining small patterns of the basic logic with WeDo+Scratch applying 4 syntax of input, operator, decision and repeat which are the basics of programming in consideration of prerequisite programming learning of non-programing major students. The learning method is to make a student produce a programmable robotics by attaching LEGO blocks with sensors, access and control it by programming. Below is the 7-step approach which is a learning method of basic program coding proposed in this study:

- Step 1: practice code blocks of input, operator, decision and repeat using icons of WeDo
- Step 2: combine the code blocks using the practiced icons of the basic syntax in many different ways to make the robot response
- Step 3: according to the response of the robotics completed based on the WeDo code blocks, execute tests or edit the codes
- Step 4: install the plug-in to interlock WeDo with scratch then do programming with scratch for the same assignment

- Step 5: interlock scratch with the robotics and test or modify
- Step 6: when there is a need to add animation or such functions available on scratch, add Scratch code blocks
- Step 7: interlock the added codes with the robotics on scratch, test and modify the codes

Above 7-step method helps developing basic programming skills for SW development by interlocking the concept of the robotics built with WeDo constructionism based LEGO Model blocks with scratch.

Literature review

WeDo: WeDo (Mayerova, 2012) is a product of LEGO group developed for fundamental learning of robotics and programming education. It makes users to build their

models with LEGO blocks and find the ways run their models using software. Users can build basic LEGO Models connectable to computer and do programming.

The software UI of WeDo is made up of connect with pc, record voice, manu tab, file options, storage, stop button and programming code blocks as in Fig. 1. And it also has 4 sensors attachable to LEGO after assembly including a motor, a motion sensor, a tilt sensor and a LEGO USB hub.

Scratch software: The scratch is a programming language created by Lifelong Kindergarten team of MIT's media lab with Yasmn Kafai team of UCLA (Clements, 1999; Olabe *et al.*, 2011; Polchow, 2014). Figure 2 shows the scratch interface. Scratch can be classified into instruction combination, instruction, sprite and result check and it is



Fig. 1: The WeDo Software interface and WeDo sensors

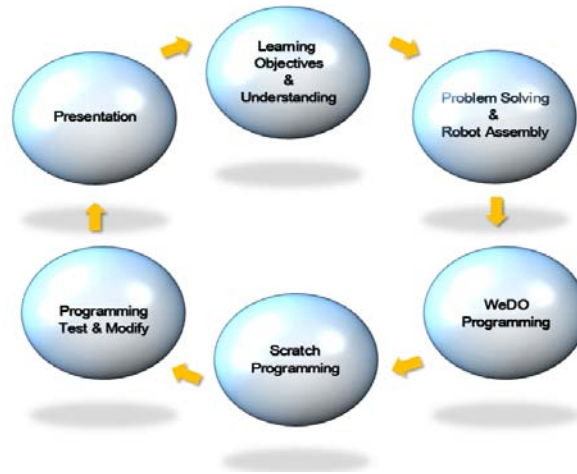


Fig. 3: Educational model using WeDo with scratch

Table 1: Curriculum based on WeDo with scratch




Education contents	Programming grammar exercise
First learn WeDo and scratch	
Products navigation	WeDo: setting exercise
Learn the role of each WeDo product	Scratch: setting exercise
Create free creations with parts	
Scratch item navigation	
Learn the role of each scratch item	
WeDo programming getting ready	
Learn about usb hub	WeDo: setting exercise
Installation of WeDo program	Scratch: setting exercise
Computer connection with WeDo	
Block assembly diagram and block classification	
Interlocking with scratch	
Moving bird: learning example 1	
Block assembly	Condition control using sensors
Controlled via WeDo Software	Change sound: change input value
Control processing according to WeDo dedicated sensor value	Use of tilt sensor: input
Controlled through scratch programming	Repeat control: loops
Challenge tilt sensor sounds through water	
Hungry crocodiles: learning example 2	
Block assembly	Condition using air sensor
Controlled via WeDo Software	Infrared sensor utilization: input
Control processing according to sensor value	Infrared sensor utilization: input
Controlled through scratch programming	Infrared sensor utilization: input
Challenge: controlling the gear through the motor and infrared sensor	Show the number of food feeds: operator
	Open the mouth of a crocodile: a loop

resolve problems during the project. Consequently, they obtain expansive thinking ability as they practice not only computing thinking but also creative thinking systematic inference and cooperation.

Combination of programming language syntax and WeDo icons: In this study, the basic logic of the programming syntax such as input, decision, operator and repeat shall be applied with WeDo icons in consideration of prerequisite programming learning. Learners anticipate operation of the robotics when using certain icons with the basic logic and apply what they learned and they conduct a test and edit the programming so that their understanding in the syntax expands. Table 2 proposes

combinations of the basic programming syntax proposed in this thesis with WeDo icons. First of all, the icons in Table 2 are input and “Icon 1~7” are the conditions that are attached on the bottom of the blocks and the icon is small and convex on the top. “Icon 1~3” are input letters, input numbers and input random value and “Icon 4~6” are input of motion sensor, tilt sensor and sound sensor each and “Icon 7” is display input. Secondly they are decision icons and “Icon 11~12” are to set up conditions to run or stop the motor. Thirdly, “Icon 13~16” are operators which users can select for the four fundamental arithmetic operations and can set up or adjust the changeable width by entering number like “Icon 2” at the bottom. And lastly, “Icon 17”

Table 2: Programming basic syntax and WeDo icon matching

Programming basic process	WeDo icon	WeDo icon description
Input	 <p>Icon1 Icon2 Icon3</p> <p>Icon4 Icon5 Icon6 Icon7</p> <p>Icon8 Icon9 Icon10</p>	Icon 1: text input Icon 2: number input Icon 3: random input Icon 4: motion sensor input Icon 5: tilt sensor input Icon 6: sound sensor input Icon 7: display input Icon 8: start block Icon 9: start on key press block Icon 10: display input
Branch	 <p>Icon 11 Icon 12</p>	Icon 11: motor on for block Icon 12: motor off block (Bottom Icon no combination)
Operator	 <p>Icon 13 Icon 14 Icon 15 Icon 16</p> <p>Combination2</p>	Icon 13: add to Display block Icon 14: subtract from display block Icon 15: multiply by display block Icon 16: divide by display block Icon 17: Repeat block (loop counting)
Loop		

is to set up repeat and users can enter a number to set up the number to repeat and if none, it does endless looping (Kazakoff *et al.*, 2013; Maloney *et al.*, 2008).

RESULTS AND DISCUSSION

Combination of WeDo icons with scratch: Scratch provides plug-in to interlock with WeDo. Users can control what they learned on WeDo software with the blocks using scratch. It is able to program the same codes which control the robotics on WeDo, on scratch and it also allows testing and editing the programming by applying the same plan for problem resolution. Through this, users learn the same syntax on WeDo and practice with scratch does so they understand the syntax easily and have stronger practical ability of programming. Also, it enhances understanding in programming since it can interlock as it shows images on a computer screen through scratch which WeDo could not do and the robot works correspondingly. Table 3 shows the same result programming based on WeDo with scratch.

Application examples: In this study, WeDo 1.2 and scratch 2 offline editor are used to test the proposed learning method. Scratch requires Adobe Air for its use and the offline editor is used which is available both online and offline. To interlock with WeDo on scratch, it needs to install the plug-in first. In scripts tab on scratch,

click more blocks-add an extension and select LEGO WeDo 1.0. When connecting the USB of WeDo after installation of the plug-in, the grey block that controls the motor is added at the bottom. The programming is done by combining the WeDo assembly sensors with scratch code blocks. In Fig. 4 is to add WeDo blocks step by step. In the first step, apply the icons with sound to change the set-up and in the next step, practice to repeat the bird sound. In the third step, adjust the angle with the tilt sensor value and set up to turn on the bird sound when it tilts. After this, change the set up to turn on the sound only when the bird picks up the feed with its head down in the fourth step. In the fifth step, set up to turn on the sound every time the bird bows down its head. And lastly in the sixth step, set up to turn on the bird sound and increase the number by one every time the bird bows down its head, display the number on the screen and add repetition. Then set up again to repeat displaying the numbers of picking up the feed and the bird sound afterwards. Practice using the icons and add them, then test the robot moving by creating patterns with the basic syntax in small ranges. In Fig. 5 is a converted code from WeDo into scratch. It executes when the start button is clicked, the 'parrot-b' images that were pre-selected in 'costume' change and the bird sound is on when the value of the tilt sensor is 0. In sequence, 'costumes' appears and it waits 0.3 sec. When the value of the tilt sensor is 0, it repeats in a cycle.

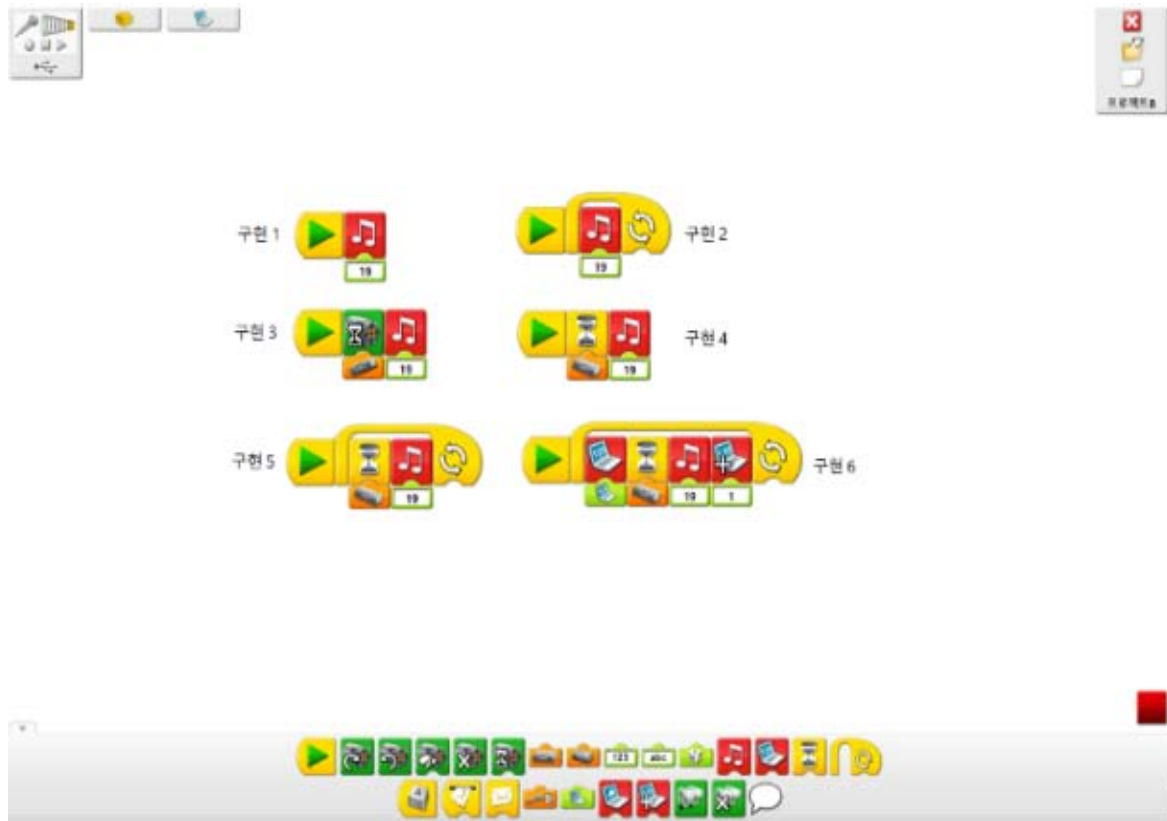

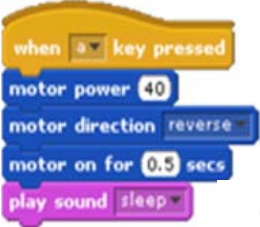

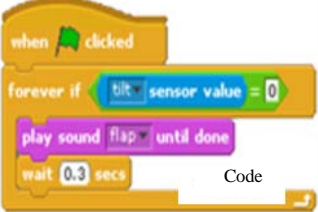


Fig. 4: WeDo additional programming step-by-step



Fig. 5: Programming based on scratch with robotics: application example

Table 3: Same result programming based on WeDo with scratch

WeDo icon	Scratch code	Descriptions
 <p>Combination 3</p>	 <p>Code 1</p>	Keyboard press start (input) Motor strength setting Motor rotation Motor standby time standby (branch) Play selected sound
 <p>Combination 2</p>	 <p>Code</p>	Start button press start (input) Depending on the tilt sensor value, Play sound selection. Sound can be changed (variable) Waiting time setting (variable) Repeat all infinite (repeat)

CONCLUSION

This study proposes the learning method to develop problem solving skills by creating and combining small patterns with the basic syntax on WeDo of LEGO and scratch as a prerequisite programming learning method for new learners who have never learned programming before. And this method has its intention to make the learners produce programmable robotics on their own by attaching the LEGO blocks with the sensors and understand the concept of SW programming using the software called Scratch. It allows more efficient programming education as the learners obtain knowledge of programming, create, evaluate and make practical use through WeDo+scratch and their cognitive structure changes through understanding. Also, it is able to check the process and the result of production in real time as the robotics and the programming are interconnected, so the learners clearly understand the content of the integral SW education. Additionally they are able to understand the linguistic characteristics and the similarities of the basic syntax of computer languages such as JAVA and C through the interconnected process of the same assignment on WeDo and scratch. The WeDo+scratch learning method is based on the curriculums that can help learners with none of programming experiences understand the basic logic effectively and do SW programming easily. However, this method is insufficient for learning the algorithm in intermediate or higher levels since it uses only the basic logic. Therefore, there is a need of further research to learn the algorithm such as SW programming and data structure in intermediate or higher levels with the WeDo+Scratch programming learning method.

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