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# Pseudo-Additive (Mixed) Fourier Series Model of Time Series 

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#### Abstract

This study improves on the Additive Fourier Series and traditional model of discrete periodic time series. It seeks to formulate a mixed (multiplicative-additive) Fourier Series model which decomposes a time series into multiplicative trend, seasonal components and additive error component together with additive trend. It is discovered that for time series with strongly marked and obviously fluctuating seasonal effects a multiplicativeadditive (mixed) Fourier series model is suitable. The relevance of the new model is shown by analyzing the rainfall data of Uyo metropolis with the use of the model. The resulting model gives $\mathrm{Y}_{\mathrm{t}}=210.1$ (1-0.984 cos $\omega t$ ) which fits well to the original data and can be used in forecasting future values of the rainfall data.


Key words: Multiplicative-additive (mixed) models, fourier series seasonal effects, forecasting, pseudo-additive model

## INTRODUCTION

Most periodic time series have been assumed to be modeled by the use of additive Fourier Series model or any other seasonal models, but not much have been done on the modeling of a special case of such time series with a strongly marked and obviously fluctuating seasonal effects. The researcher discovered that for such time series a pseudo-additive (mixed) Fourier series model is very suitable. The development is as a result of the work of Hernmann et al. (2006), who demonstrated that a series with sharply pronounced seasonal fluctuations and trend-cycles movement, which is extremely weather-dependent could be modeled suitably using a multiplicative-additive (Mixed) model given by $\mathrm{Y}_{\mathrm{t}}=\mathrm{D}\left(\mathrm{C}_{\mathrm{t}}+\mathrm{S}_{\mathrm{t}}+\mathrm{I}_{\mathrm{t}}\right)$. The further said that this can be implemented in X-12-ARIMA. In a similar development, Findley et al. (1998) earlier suggested a Pseudo-additive decomposition with a relative working day factor (D) as $\mathrm{Y}_{\mathrm{t}}=\mathrm{C}_{\mathrm{t}} \mathrm{D}_{\mathrm{t}}\left(\mathrm{S}_{\mathrm{t}}+\mathrm{I}_{\mathrm{t}}^{-1}\right)$, which made it possible to estimate relative calendar factors based on a logarithmic REGARIMA model. Traditionally, time series are decomposed into four basic components: the trend, seasonal, cyclical and irregular components. Nkpodot and Usoro (2005) stated three traditional models of time series as completely additive, completely multiplicative and mixed models. They outlined the models mathematically as:

- $\mathrm{Y}_{\mathrm{t}}=\mathrm{C}_{\mathrm{t}}+\mathrm{S}_{\mathrm{t}}+\mathrm{I}_{\mathrm{t}}$-completely additive model
- $\mathrm{Y}_{\mathrm{t}}=\mathrm{C}_{\mathrm{t}} \mathrm{S}_{\mathrm{t}} \mathrm{I}_{\mathrm{t}}$-completely multiplicative model
- $\mathrm{Y}_{\mathrm{t}}=\mathrm{C}_{\mathrm{t}} \mathrm{S}_{\mathrm{t}}+\mathrm{I}_{\mathrm{t}}$-Mixed model.

Where:
$\mathrm{Y}_{\mathrm{t}}=$ Observation at time t
$C_{t}=$ Current mean or trend-cycle effect
$S_{t}=$ Seasonal effect
$\mathrm{I}_{\mathrm{t}}=$ Residual or random error.

Also in time series analysis, it is assumed that an unadjusted series (Y) may be decomposed into four unobservable components. The first of those is the trend cycle component (C), which includes not just the long-term trend but also cyclical fluctuations. Then comes the calendar component (D), derived from the effects of working-day variations, for example. There is additionally the seasonal component (S), which includes annual fluctuations that recur to almost the same degree in the same period (Anonymous, 2001).

According to Priestly (1981), one of the most important advantages of Fourier Series Analysis is its simple way of modeling a series with seasonality or cyclicalness. He further said that Fourier series method can be used to model seasonal effects using several seasonal peaks per year.

Chatfield (1975), stated that a seasonal component of a time series can be decomposed into underlying sine and cosine functions of different frequencies known as Fourier series. One way of doing this is to cast the issue as a linear multiple regression problem, where the dependent variable is the detrended time series and the independent variable are the sine and cosine functions of all possible (discrete) frequencies (Priestly, 1981).

Roerink et al. (2000) used Fourier Series Analysis or Harmanic Analysis of Time Series to screen and remove cloud affected observations and temporarily interpolate the remaining observations to reconstruct gapless images at a prescribed time.

## METHODS OF ANALYSIS

The analysis of this study is done through the help of a statistical package called MINITAB. The model is given by:

$$
\begin{gather*}
Y_{t}=\left(a_{0}+b_{0} t\right) \sum_{i=1}^{k}\left[a_{i} \cos i \omega t+b_{i} \sin i \omega t\right]+\left(a_{0}+b_{0} t\right)+e_{t}  \tag{1}\\
Y_{t}=\left(a_{0}+b_{0} t\right)\left[\sum_{i=1}^{k}\left[a_{i} \cos i \omega t+\sin i \omega t\right]+1\right]+e_{t} \tag{2}
\end{gather*}
$$

The estimated model is given by:

$$
\begin{equation*}
\hat{Y}_{t}=\left(a_{0}+b_{0} t\right)\left[\sum_{i=1}^{k}\left[a_{i} \cos i \omega t+\sin i \omega t\right]+1\right] \tag{3}
\end{equation*}
$$

Where:
$\mathrm{Y}_{\mathrm{t}}=$ The observation at time t
$\mathrm{b}_{0}=$ The trend parameter estimate
$\mathrm{a}_{0}=$ The constant used to set the level of the series
$\mathrm{a}_{\mathrm{i}}=$ The parameter estimates.
$e_{t}=$ The error term
$\omega=2 \pi \mathrm{f} / \mathrm{n}$

Where:
$\mathrm{f}=$ The fourier frequency
$\mathrm{k}=$ The highest harmonic

It is noteworthy here that the highest harmonic, k in Fourier Series Analysis model is the number of observations per season divided by two (2) for an even number of observation and $\mathrm{n}-1 / 2$ for an odd number of observations.

Hence; The model given above can be represented traditionally as

$$
\mathrm{Y}_{\mathrm{t}}=\mathrm{T}_{\mathrm{t}}\left(\mathrm{~S}_{\mathrm{t}}+1\right) \mathrm{I}_{\mathrm{t}}=\mathrm{T}_{\mathrm{t}} \mathrm{~S}_{\mathrm{t}} \mathrm{I}_{\mathrm{t}}+\mathrm{T}_{\mathrm{t}} \mathrm{I}_{\mathrm{t}}
$$

$\mathrm{T}=\mathrm{a}_{0}+\mathrm{b}_{0} \mathrm{t}$ is used in estimating the trend, while the expressions containing the sine and cosine terms gives the estimated model for seasonality. The method used in estimating the parameters of the model is the method of least squares in Multiple Regression Analysis. Firstly the trend is removed from the series by multiplicative procedure:

$$
\begin{equation*}
\frac{Y_{t}}{a_{0}+b_{0} t}=\sum_{i=1}^{k}\left(a_{i} \cos i \omega t+b_{i} \sin i \omega t\right)+e_{t}=D T \tag{5}
\end{equation*}
$$

Then DT (the detrended series) is then estimated by method of ordinary least squares

$$
\begin{equation*}
D T=\sum_{i=1}^{k}\left(a_{i} \operatorname{cosi} \omega t+b \sin i \omega t\right) \tag{6}
\end{equation*}
$$

A statistical test of significance of the general model and that of the parameter estimates are done using a computer package known as MINITAB.

It is noted here that if the trend parameter $b_{0}$ is not significant (i.e., $b_{0}=0$ ), then the estimated model becomes.

$$
\begin{equation*}
\hat{Y}_{t}=a_{0}\left[\sum_{i=1}^{k}\left(a_{i} \cos i \omega t+b_{i} \sin i \omega t+1\right]\right. \tag{7}
\end{equation*}
$$

## DATA ANALYSIS

From the trend analysis,
$\mathrm{b}_{0} \quad=0$
$\mathrm{a}_{0} \quad=210.1$
Therefore $\mathrm{T}=\mathrm{a}_{0}=210.1$
Also, since
$\mathrm{k}=6, \mathrm{I}=1,2,3, \ldots, 6 \mathrm{I}=1$ and $\omega=\pi / 6$
Therefore,

$$
D T=\sum_{i=1}^{6}\left(a_{i} \cos i \frac{\pi}{6} t+b_{i} \sin i \frac{\pi}{6} t\right)
$$

is modeled using in Table 1 and 2:
From Table 1, the estimated model with the significant parameter estimates is; DT $=-0.984 \cos \omega$.

Table 1: Results for testing the signific ance of the detrended series model

| Predictor noconstant | Coefficient | SD | T | p |
| :--- | :---: | :--- | :---: | :--- |
| coswt | -0.98370 | 0.13350 | -7.37 | 0.000 |
| sinwt | -0.21840 | 0.13350 | -1.64 | 0.105 |
| $\cos 2 \mathrm{wt}$ | -0.15270 | 0.13350 | -1.14 | 0.255 |
| $\sin 2 \mathrm{wt}$ | 0.09850 | 0.13350 | 0.74 | 0.462 |
| $\cos 3 \mathrm{wt}$ | 0.09670 | 0.13350 | 0.72 | 0.470 |
| $\sin 3 \mathrm{wt}$ | 0.00520 | 0.13350 | 0.04 | 0.969 |
| $\cos 4 \mathrm{wt}$ | 0.19540 | 0.13350 | 1.46 | 0.146 |
| $\sin 4 \mathrm{wt}$ | 0.01570 | 0.13350 | 0.12 | 0.907 |
| $\cos 5 \mathrm{wt}$ | -0.13060 | 0.13350 | -0.98 | 0.330 |
| $\sin 5 \mathrm{wt}$ | -0.02700 | 0.13350 | -0.20 | 0.840 |
| $\cos 6 \mathrm{wt}$ | 0.03203 | 0.09440 | 0.34 | 0.735 |

Table 2: Result for testing the significance of general detrended series model

| Source | df | SS | MS | F | p |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Regression | 11 | 66.961 | 6.087 | 5.69 | 0.000 |
| Error | 109 | 116.567 | 1.069 |  |  |
| Total | 120 | 183.527 |  |  |  |



Fig. 1: Plot of actual and estimated values

## RESULTS AND DISCUSSION

From the above analysis, the general estimated model is obtained as $\mathrm{Y}_{\mathrm{t}}=210.1(-0.984 \cos \omega \mathrm{t}+1)$ or $Y_{t}=210.1-206.728$ cosùt. The plot of the actual and fitted values of the rainfall data is given in Fig. 1. The plot indicates a good fit of the model.

It is a known fact that there are many models used in modeling a periodic time series. In this study, developments are made in the use of Fourier Series model to fit a time series. It is discovered that a pseudo-additive Fourier series model so developed is quite suitable for the modeling and forecasting of a time series with strongly marked and obviously fluctuating seasonal effects. This is shown in Appendix 1 and 2, where the estimated values fit well to the actual values.

|  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ |
| 1 | 6.2 | 25 | 6.2 | 49 | 8.8 | 73 | 5.3 | 97 | 4.8 |
| 2 | 56.0 | 26 | 55.0 | 50 | 50.9 | 74 | 55.0 | 98 | 45.0 |
| 3 | 200.4 | 27 | 219.0 | 51 | 224.1 | 75 | 225.3 | 99 | 230.0 |
| 4 | 290.0 | 28 | 300.1 | 52 | 310.0 | 76 | 299.0 | 100 | 287.4 |
| 5 | 273.0 | 29 | 280.0 | 53 | 268.2 | 77 | 273.0 | 101 | 277.0 |
| 6 | 450.0 | 30 | 438.0 | 54 | 440.0 | 78 | 433.0 | 102 | 444.2 |
| 7 | 371.0 | 31 | 372.0 | 55 | 382.0 | 79 | 372.0 | 103 | 356.0 |
| 8 | 396.0 | 32 | 396.6 | 56 | 396.2 | 80 | 400.7 | 104 | 389.0 |
| 9 | 320.5 | 33 | 323.3 | 57 | 325.0 | 81 | 328.4 | 105 | 333.3 |
| 10 | 89.1 | 34 | 87.4 | 58 | 100.0 | 82 | 92.6 | 106 | 92.1 |
| 11 | 10.9 | 35 | 14.0 | 59 | 15.0 | 83 | 10.0 | 107 | 12.4 |
| 12 | 14.0 | 36 | 9.9 | 60 | 3.5 | 84 | 5.8 | 108 | 10.0 |
| 13 | 4.5 | 37 | 0.0 | 61 | 2.9 | 85 | 5.7 | 109 | 0.2 |
| 14 | 60.5 | 38 | 45.0 | 62 | 53.8 | 86 | 57.0 | 110 | 41.8 |
| 15 | 221.3 | 39 | 222.0 | 63 | 225.1 | 87 | 222.0 | 111 | 216.8 |
| 16 | 299.0 | 40 | 297.0 | 64 | 295.7 | 88 | 296.5 | 112 | 290.0 |
| 17 | 271.0 | 41 | 277.0 | 65 | 273.2 | 89 | 272.0 | 113 | 268.0 |
| 18 | 439.0 | 42 | 439.5 | 66 | 400.0 | 90 | 436.0 | 114 | 442.0 |
| 19 | 372.0 | 43 | 372.1 | 67 | 372.0 | 91 | 300.0 | 115 | 372.0 |
| 20 | 400.0 | 44 | 397.0 | 68 | 395.0 | 92 | 388.9 | 116 | 403.0 |
| 21 | 331.0 | 45 | 328.0 | 69 | 323.6 | 93 | 323.1 | 117 | 321.4 |
| 22 | 90.1 | 46 | 88.0 | 70 | 88.0 | 94 | 90.3 | 118 | 97.0 |
| 23 | 15.0 | 47 | 12.0 | 71 | 9.0 | 95 | 11.6 | 119 | 12.7 |
| 24 | 10.0 | 48 | 10.0 | 72 | 11.2 | 96 | 12.5 | 120 | 1.1 |


| Appendix 2: Fitted values (Y) |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ | S. No. | $\mathrm{Y}_{\mathrm{t}}$ |
| 1 | 7.663 | 25 | 7.664 | 49 | 7.665 | 73 | 7.665 | 97 | 7.666 |
| 2 | 55.189 | 26 | 55.195 | 50 | 55.200 | 74 | 55.206 | 98 | 55.211 |
| 3 | 223.775 | 27 | 223.786 | 51 | 223.797 | 75 | 223.808 | 99 | 223.819 |
| 4 | 299.682 | 28 | 299.678 | 52 | 299.675 | 76 | 299.671 | 100 | 299.667 |
| 5 | 276.425 | 29 | 276.432 | 53 | 276.438 | 77 | 276.445 | 101 | 276.452 |
| 6 | 439.364 | 30 | 439.368 | 54 | 439.371 | 78 | 439.375 | 102 | 439.379 |
| 7 | 367.324 | 31 | 367.319 | 55 | 367.314 | 79 | 367.309 | 103 | 367.304 |
| 8 | 399.429 | 32 | 399.434 | 56 | 399.438 | 80 | 399.443 | 104 | 399.447 |
| 9 | 328.992 | 33 | 328.979 | 57 | 328.967 | 81 | 328.954 | 105 | 328.941 |
| 10 | 94.682 | 34 | 94.672 | 58 | 94.663 | 82 | 94.653 | 106 | 94.643 |
| 11 | 15.463 | 35 | 15.462 | 59 | 15.462 | 83 | 15.461 | 107 | 15.460 |
| 12 | 12.006 | 36 | 12.005 | 60 | 12.005 | 84 | 12.004 | 108 | 12.004 |
| 13 | 7.664 | 37 | 7.664 | 61 | 7.665 | 85 | 7.666 | 109 | 7.666 |
| 14 | 55.192 | 38 | 55.197 | 62 | 55.203 | 86 | 55.209 | 110 | 55.214 |
| 15 | 223.781 | 39 | 223.792 | 63 | 223.803 | 87 | 223.814 | 111 | 223.825 |
| 16 | 299.680 | 40 | 299.676 | 64 | 299.673 | 88 | 299.669 | 112 | 299.665 |
| 17 | 276.428 | 41 | 276.435 | 65 | 276.442 | 89 | 276.448 | 113 | 276.455 |
| 18 | 439.366 | 42 | 439.369 | 66 | 439.373 | 90 | 439.377 | 114 | 439.381 |
| 19 | 367.321 | 43 | 367.316 | 67 | 367.311 | 91 | 367.306 | 115 | 367.301 |
| 20 | 399.431 | 44 | 399.436 | 68 | 399.440 | 92 | 399.445 | 116 | 399.449 |
| 21 | 328.986 | 45 | 328.973 | 69 | 328.960 | 93 | 328.948 | 117 | 328.935 |
| 22 | 94.677 | 46 | 94.667 | 70 | 94.658 | 94 | 94.648 | 118 | 94.639 |
| 23 | 15.463 | 47 | 15.462 | 71 | 15.461 | 95 | 15.461 | 119 | 15.460 |
| $\underline{24}$ | 12.006 | 48 | 12.005 | 72 | 12.005 | 96 | 12.004 | 120 | 12.008 |

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