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## A Mathematical Model of Fuzzy Multiple Objective Programming and Applications

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**Abstract:** For multiple objective programming problems with many constraint conditions, an improved objective programming approach is built up with fuzzy mathematics. First solve the deviation variables based on the priority level of the objectives and then determine the upper bound of the flexible indexes by considering the deviation variables. Hence, build up the mathematical model of fuzzy multiple objective programming and it can be applied to realistic transportation problems in which satisfactory results can be drawn.

**Key words:** Objective programming approach, priority level, fuzzy multiple objective programming, flexible indexes, satisfactory solution

### INTRODUCTION

The goal programming, which can be used to deal with the problems in which containing a single main objective and multiple sub-objectives, or multiple main objectives and multiple sub-objectives. Previously, every object is assigned with an expected value and when they satisfy some constraint conditions of the system, the solutions which are most closed to the expected values can be found. By this method, the objects set by decision makers can be entirely reflected in the system model and subjective willing can be unified with objective possibility in one mathematical model.

When the calculation was processed, the deviation variable of goal programming was so large that the solution was not accurate enough. Since the objectives in multi-objective programming can be sorted as required goals and expected goals, where the required goals have veto and the expected goals are elastic in hierarchy of objectives. Because the goal constraint in multi-objective programming is a type of soft constraint which can be elastic, so we adopt a fuzzy mathematical method by introducing fuzzy programming with elastic constraint conditions into multi-objective programming, hence more satisfactory solutions can be gained (Kaicheng, 2004).

### METHOD AND MODEL

Only multi-objective programming problems will be discussed.

**Mathematical model for goal programming:** In multi-objective optimization problems, since the objectives have connections and conflicts between each

other, we need to distinguish main objectives and secondary objectives and sort multi-objective into different levels. The priority levels are represented by  $P_1, P_2, \dots, P_m$ . Only when the objectives corresponding to higher priority factors are satisfied, the objectives with lower priority factors can be considered. For those objectives with the same priority level, the importance can be represented by their weight coefficient. (Changbing, 2007).

For every decision goal, we introduced deviation variables  $d^+$  and  $d^-$  to represent the part that decision value exceeds or lack to the expectation value. And it is defined as  $d^+ \geq 0, d^- \geq 0$ .

The objective function consists of the deviation variables of goal constraint and their corresponding priority factors  $P_i$ , as well as the weight coefficients. Because goal programming pursues the solution that is closed to some given expectation value, which means that every corresponding deviation variable should be as small as possible, so the objective function should be minimized. The mathematical model is built up as:

$$\min \{P_1 (\sum_{k=1}^K (W_k^- d^- + W_k^+ d^+)), 1=1, 2, \dots, L\}$$

$$\begin{cases} \sum_{j=1}^n c_{kj} x_j + d_k^- - d_k^+ = g_k, k=1, 2, \dots, K \\ \sum_{j=1}^n a_{ij} x_j \leq (=, \geq) b_i, i=1, 2, \dots, m \\ x_j \geq 0, j=1, 2, \dots, n \\ d_k^+, d_k^- \geq 0, k=1, 2, \dots, K \end{cases} \quad (1)$$

where,  $g_k$  is the expectation value of the  $k$ -th goal constraint;  $W_k^-, W_k^+$  are weights of the goals corresponding to  $P_1$  priority level and  $P_1 \gg P_2 \gg \dots \gg P_m$ .

**Mathematical model for fuzzy multi-objective programming:** Here we take the idea of fuzzy linear programming into goal programming. First, we gain the optimal value  $f_{i_0}$  ( $i = 1, 2, \dots, l$ ) of each objective function:

$$f_i = \sum_{j=1}^n c_{ij}x_j$$

under the same constraint condition. If the expectation value of goal constraint is given, we can omit this step and then solve the deviation variable according to the priority level of goals. By considering the deviation variable the upper limit of the flexible index  $d_i \geq 0$  can be determined and the corresponding fuzzy goal set  $\tilde{G}_i$  can be gained, whose subordinate function is defined as:

$$\tilde{G}_i(x) = \begin{cases} 0, & \sum_{j=1}^n c_{ij}x_j < f_{i_0} - d_i; \\ 1 - \frac{1}{d_i}(f_{i_0} - \sum_{j=1}^n c_{ij}x_j), & f_{i_0} - d_i < \sum_{j=1}^n c_{ij}x_j < f_{i_0}; \\ 1, & \sum_{j=1}^n c_{ij}x_j \geq f_{i_0}. \end{cases}$$

Take:

$$\tilde{G} = \bigcap_{i=1}^L \tilde{G}_i, A$$

as the feasible solution set satisfying the constraint conditions and solve  $X^*$  according to maximum subordination principle, such that:

$$\tilde{G}(x^*) = \max_{x \in A} \{ \tilde{G}(x) \}$$

It equals to solving the normal linear programming problem:

$$\begin{cases} \max \lambda; \\ 1 - \frac{1}{d_i}(f_{i_0} - \sum_{j=1}^n c_{ij}x_j) \geq \lambda, i=1,2,\dots,l; \\ \sum_{j=1}^n a_{kj}x_j \leq b_k, k=1,2,\dots,m; \\ \lambda \geq 0, x_1 \geq 0, x_2 \geq 0, \dots, x_n \geq 0. \end{cases} \quad (2)$$

The key of this problem is the determination of the flexible index  $d_i \geq 0$ . We combine the goal programming method in Eq. 1 and the fuzzy multi-objective programming in Eq. 2 and determine the appropriate  $d_i \geq 0$ , hence gain the optimal solution closed to the goal expectation within the feasible region.

### A TRANSPORTATION PROBLEM CASE

A transportation enterprise provides the service that transport steels from steel producing enterprises in 3 different cities to 4 real estate enterprises in different cities. The steel producing enterprises  $A_i$  ( $i = 1, 2, 3, 4$ ) have supply of  $a_i$  while the real estate enterprises  $B_j$  ( $j = 1, 2, 3, 4$ ) have demand of  $b_j$ . The unit transportation fee  $c_{ij}$  is listed in Table 1.

When making the transportation schedule, these 6 goals should be considered by priority level:

$P_1$ : The real estate enterprise  $B_4$  is an important enterprise, its demand should be satisfied;  $P_2$ : The steel producing enterprise  $A_3$  should supply no less than 100 to  $B_1$ ;  $P_3$ : Every real estate enterprise should get steels no less than 75~85% of its demand;  $P_4$ : The real total fee should be less than 110% of the minimum transportation fee without considering goals  $P_1$  to  $P_5$ ;  $P_5$ : Supply to  $B_1$  and  $B_3$  should be the same or similar;  $P_6$ : The total transportation fee should be minimized (Jiuping, 2009).

This is a transportation problem with unbalanced supply and demand. First we suppose transportation fee from  $A_i$  to  $B_j$  is  $x_{ij}$ , so the minimized fee is 2950 without considering goals  $P_1$  to  $P_5$ . The minimum fee by goal programming is 3170 if  $P_1$  to  $P_6$  are considered (Yunqian, 2004; Anderson *et al.*, 2003).

We use the improved fuzzy goal programming. The deviation variables  $d_i$  of goal constraint can be treated as the upper limit of flexible index in fuzzy linear programming. The mathematical model is as follow:

$$\begin{aligned} \min f = & 5x_{11} + 2x_{12} + 6x_{13} + 7x_{14} + 3x_{21} \\ & + 5x_{22} + 4x_{23} + 6x_{24} + 4x_{31} + 5x_{32} + 2x_{33} + 3x_{34} \end{aligned}$$

Constraint conditions:

$$\begin{cases} x_{11} + x_{12} + x_{13} + x_{14} \leq 300 \\ x_{21} + x_{22} + x_{23} + x_{24} \leq 200 \\ x_{31} + x_{32} + x_{33} + x_{34} \leq 400 \\ x_{11} + x_{21} + x_{31} \leq [200, 10] \\ x_{12} + x_{22} + x_{32} \leq [100, 5] \\ x_{13} + x_{23} + x_{33} \leq [450, 25] \\ x_{14} + x_{24} + x_{34} \leq [250, 15] \\ x_{31} \geq [100, 5] \\ x_{11} + x_{21} + x_{31} \geq [160, 10] \\ x_{12} + x_{22} + x_{32} \geq [80, 5] \\ x_{13} + x_{23} + x_{33} \geq [360, 25] \\ x_{14} + x_{24} + x_{34} \geq [200, 15] \\ \frac{x_{11} + x_{21} + x_{31}}{200} + \frac{x_{13} + x_{23} + x_{33}}{450} = [0, 0.1] \end{cases}$$

Table 1: Unit transportation fee (Transportation unit in ton, fee unit in thousand dollars)

$c_{ij}$	$B_1$	$B_2$	$B_3$	$B_4$	$a_i$
$A_1$	5	2	6	7	300
$A_2$	3	5	4	6	200
$A_3$	4	5	2	3	400
$b_j$	200	100	450	250	

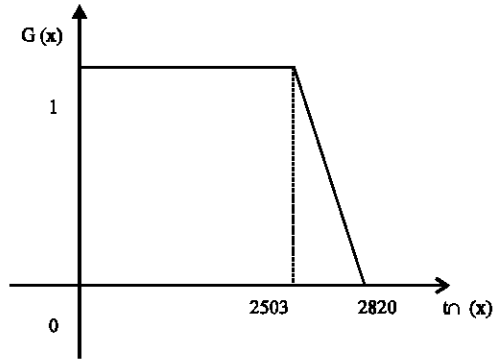


Fig. 1: Plot of the subordinate function

The equations can break up to two normal linear programming problems. By LINGO software we obtain two sets of optimal solutions:

$$f_0 = 2820, f_1 = 2503, d_0 = f_0 - f_1 = 317$$

The subordinate function of the objective function is plotted as Fig. 1.

Solve the normal linear programming:  $\max \lambda$  with constraint conditions:

$$\begin{cases} 5x_{11} + 2x_{12} + 6x_{13} + 7x_{14} + 3x_{21} + 5x_{22} + 4x_{23} \\ + 6x_{24} + 4x_{31} + 5x_{32} + 2x_{33} + 3x_{34} - 317\lambda \leq 2820 \\ x_{11} + x_{12} + x_{13} + x_{14} \leq 300 \\ x_{21} + x_{22} + x_{23} + x_{24} \leq 200 \\ x_{31} + x_{32} + x_{33} + x_{34} \leq 400 \\ x_{11} + x_{21} + x_{31} + 10\lambda \leq 210 \\ x_{12} + x_{22} + x_{32} + 5\lambda \leq 105 \\ x_{13} + x_{23} + x_{33} + 25\lambda \leq 475 \\ x_{14} + x_{24} + x_{34} + 15\lambda \leq 265 \\ x_{31} - 5\lambda \geq 95 \\ x_{11} + x_{21} + x_{31} - 10\lambda \geq 150 \\ x_{12} + x_{22} + x_{32} - 25\lambda \geq 75 \\ x_{13} + x_{23} + x_{33} - 25\lambda \geq 335 \\ x_{14} + x_{24} + x_{34} - 15\lambda \geq 185 \\ \frac{x_{11} + x_{21} + x_{31}}{200} + \frac{x_{13} + x_{23} + x_{33}}{450} - 0.1\lambda \geq -0.1 \\ \frac{x_{11} + x_{21} + x_{31}}{200} + \frac{x_{13} + x_{23} + x_{33}}{450} + 0.1\lambda \leq 0.1 \end{cases}$$

Solve the linear programming by the software LINGO to get the optimal solution 2674, with the value of  $\lambda$  is 0.96 and the plan is:

$$x_{12} = 79, x_{13} = 118, x_{23} = 200, x_{31} = 159, x_{33} = 40, x_{34} = 199$$

Thus, we can gain the fuzzy optimal solution of the problem is 2674.

Calculation of estimate matrix is shown in appendix and program code are also presented.

### CONCLUSION

Compared with solutions of other multi-objective programming, the method of goal programming can solve the problems with different dimensions and the objectives can be modified more flexibly and instantaneously; at the meantime there would be very little additional calculation caused by the new objectives. Hence it is suitable for the changing situation of the current economics and has been a new type of tool to solving multi-objective programming.

### APPENDIX

**Appendix 1:** Calculation of estimate matrix  $\lambda_{\max}$ : 7.0164

d	G1	G2	G3	G4	G5	G6	G7	Wi
G1	1.0000	1.4918	1.8221	2.2255	2.7183	3.3201	4.0552	02746
G2	0.6703	1.0000	1.4918	1.8221	2.2255	2.7183	3.3201	02123
G3	0.5488	0.6703	1.0000	1.2214	1.4918	1.8221	2.2255	01464
G4	0.4493	0.5488	0.8187	1.0000	1.4918	1.8221	1.8221	01239
G5	0.3679	0.4493	0.6703	0.6703	1.0000	1.2214	1.4918	00954
G6	0.3012	0.3679	0.5488	0.5488	0.8187	1.0000	1.4918	00504
G7	0.2466	0.3012	0.4493	0.5488	0.6703	0.6703	1.0000	00639

### PROGRAM CODE

**Model:**

$$\min = d13;$$

```
x11+x12+x13+x14<=300;
x21+x22+x23+x24<=200;
x31+x32+x33+x34<=400;
x11+x21+x31+d1_-d1=200;
x12+x22+x32+d2_-d2=100;
x13+x23+x33+d3_-d3=450;
x14+x24+x34+d4_-d4=250;
x31+d5_-d5=100;
x11+x21+x31+d6_-d6=160;
x12+x22+x32+d7_-d7=80;
x13+x23+x33+d8_-d8=360;
x14+x24+x34+d9_-d9=200;
5*x11+2*x12+6*x13+7*x14+3*x21+5*x22+4*x23+6*x24+
4*x31+5*x32+2*x33+3*x34+d10_-d10=3245;
x24+d11_-d11=0;x11+x21+x31-0.4444444444444444*x13-
0.4444444444444444*x33+d12_-d12=0;
```

```

5*x11+2*x12+6*x13+7*x14+3*x21+5*x22+4*x23+6*x24+
4*x31+5*x32+2*x33+3*x34+d13_-d13=2950;
d4_ = 0;
d5_ = 0;
d6_+d7_+d8_+d9_ = 0;
d10 = 0;
d11 = 0;
d12_+d12 = 0;
end

```

```

Row slack or surplus dual price
1 220.0000 -1.000000
2 50.00000 0.000000
3 0.000000 2.000000
4 0.000000 4.000000
5 0.000000 0.000000
6 0.000000 0.000000
7 0.000000 0.000000
8 0.000000 -7.000000
9 0.000000 -3.000000
10 0.000000 -5.000000
11 0.000000 -2.000000
12 0.000000 -6.000000
13 0.000000 0.000000
14 0.000000 0.000000
15 0.000000 0.000000
16 0.000000 0.000000
17 0.000000 1.000000
18 0.000000 7.000000
19 0.000000 3.000000
20 0.000000 6.000000
21 0.000000 0.000000
22 0.000000 0.000000
23 0.000000 0.000000

```

Global optimal solution found at iteration: 0

Objective value: 220.0000

Variable Value Reduced Cost

```

D13 220.0000 0.000000
X11 0.000000 0.000000
X12 80.00000 0.000000
X13 0.000000 0.000000
X14 170.0000 0.000000
X21 60.00000 0.000000
X22 0.000000 5.000000
X23 140.0000 0.000000
X24 0.000000 1.000000
X31 100.0000 0.000000
X32 0.000000 7.000000
X33 220.0000 0.000000
X34 80.00000 0.000000
D1_ 40.00000 0.000000
D1 0.000000 0.000000
D2_ 20.00000 0.000000
D2 0.000000 0.000000
D3_ 90.00000 0.000000
D3 0.000000 0.000000
D4_ 0.000000 0.000000
D4 0.000000 7.000000
D5_ 0.000000 0.000000
D5 0.000000 3.000000
D6_ 0.000000 1.000000
D6 0.000000 5.000000
D7_ 0.000000 4.000000
D7 0.000000 2.000000
D8_ 0.000000 0.000000
D8 0.000000 6.000000
D9_ 0.000000 6.000000
D9 50.00000 0.000000
D10_ 75.00000 0.000000
D10 0.000000 0.000000
D11_ 0.000000 0.000000
D11 0.000000 0.000000
D12_ 0.000000 0.000000
D12 0.000000 0.000000
D13_ 0.000000 1.000000

```

```

Model:
min=d12_+d12;
x11+x12+x13+x14<=300;
x21+x22+x23+x24<=200;
x31+x32+x33+x34<=400;
x11+x21+x31+d1_-d1=200;
x12+x22+x32+d2_-d2=100;
x13+x23+x33+d3_-d3=450;
x14+x24+x34+d4_-d4=250;
x31+d5_-d5=100;
x11+x21+x31+d6_-d6=160;
x12+x22+x32+d7_-d7=80;
x13+x23+x33+d8_-d8=360;
x14+x24+x34+d9_-d9=200;
5*x11+2*x12+6*x13+7*x14+3*x21+5*x22+4*x23+6*x24+
4*x31+5*x32+2*x33+3*x34+d10_-d10=3245;
x24+d11_-d11=0;
x11+x21+x31-0.4444444444444444*x13-
0.4444444444444444*x23-
0.4444444444444444*x33+d12_-d12=0;
5*x11+2*x12+6*x13+7*x14+3*x21+5*x22+4*x23+6*x24+
4*x31+5*x32+2*x33+3*x34+d13_-d13=2950;
d4_ = 0;
d5_ = 0;
d6_+d7_+d8_+d9_ = 0;
d10 = 0;

```

d11 = 0;  
end

Global optimal solution found at iteration: 34

Objective value: 0.000000

Variable Value Reduced Cost

D12\_ 0.000000 1.000000  
D12 0.000000 1.000000  
X11 0.000000 0.000000  
X12 80.00000 0.000000  
X13 0.000000 0.000000  
X14 207.5000 0.000000  
X21 60.00000 0.000000  
X22 0.000000 0.000000  
X23 102.5000 0.000000  
X24 0.000000 0.000000  
X31 100.0000 0.000000  
X32 0.000000 0.000000  
X33 257.5000 0.000000  
X34 42.50000 0.000000  
D1\_ 40.00000 0.000000  
D1 0.000000 0.000000  
D2\_ 20.00000 0.000000  
D2 0.000000 0.000000  
D3\_ 90.00000 0.000000  
D3 0.000000 0.000000  
D4\_ 0.000000 0.000000  
D4 0.000000 0.000000  
D5\_ 0.000000 0.000000  
D5 0.000000 0.000000  
D6\_ 0.000000 0.000000  
D6 0.000000 0.000000  
D7\_ 0.000000 0.000000  
D7 0.000000 0.000000  
D8\_ 0.000000 0.000000  
D8 0.000000 0.000000  
D9\_ 0.000000 0.000000  
D9 50.00000 0.000000  
D10\_ 0.000000 0.000000  
D10 0.000000 0.000000  
D11\_ 0.000000 0.000000  
D11 0.000000 0.000000  
D13\_ 0.000000 0.000000  
D13 295.0000 0.000000

Row slack or surplus dual price

1 0.000000 -1.000000  
2 12.50000 0.000000  
3 37.50000 0.000000  
4 0.000000 0.000000  
5 0.000000 0.000000  
6 0.000000 0.000000  
7 0.000000 0.000000  
8 0.000000 0.000000  
9 0.000000 0.000000  
10 0.000000 0.000000  
11 0.000000 0.000000  
12 0.000000 0.000000  
13 0.000000 0.000000  
14 0.000000 0.000000  
15 0.000000 0.000000  
16 0.000000 0.000000  
17 0.000000 0.000000  
18 0.000000 0.000000  
19 0.000000 0.000000  
20 0.000000 0.000000  
21 0.000000 0.000000  
22 0.000000 0.000000

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