



# Journal of Applied Sciences

ISSN 1812-5654

**science**  
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## An Investigation of Causation: The Unreplicated Linear Functional Relationship Model

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**Abstract:** This study investigates the Unreplicated Linear Functional Relationship (ULFR) model where the measurement error term,  $\delta$ , is introduced. The coefficient of determination (COD) of ULFR, denoted by  $R_F^2$  is proposed and its properties are investigated. When the introduction of  $\delta$  increases significantly the COD, we say that the causation factor has been incorporated into the independent variable. Present result on the Malaysian road accident data illustrates the causal relationship between the socio-biological factors and road accident may be explained.

**Key words:** Causation, functional relationship, coefficient of determination, road accident

### INTRODUCTION

The seriousness of the road accident problem warrants a deeper investigation into the possible causes. In particular the ULFR model is investigated. The studies of functional and structural relationships have been focused on estimating the parameters and the measurement error models since it was first introduced by Adcock in year 1877 (Sprenst, 1990). Several methods were proposed, but the widely used estimator is the maximum likelihood method (Dolby, 1976; Fuller, 1987; Kendall and Stuart, 1979). An early study to check the adequacy of the ULFR model is given by Fuller (1987) who suggests using the residual plot as an indication of nonlinearity, lack of homogeneity of the error variances, nonnormality of the errors and outlier observations. In this study we propose the COD as a measure to check the model adequacy and the assumption of independent variable. Without loss of generality, the properties of this measurement for case  $\lambda = 1$  is investigated. A large value of COD of the ULFR relative to the COD of ordinary Simple Linear (SL) regression model is indicative of causation.

As pointed out by Fuller (1987), the assumption that the independent variable can be measured exactly may not be realistic in many situations. The estimates of independent variable may contain measurement error arising from trying to quantify a variable that has no physical dimension. For example in the road accident problem, it has been shown that the male motorist is more prone to be involved in accident. One possible explanation is the performance of male drivers may vary with state of mind. Since this factor, the state of mind

cannot be measured directly, it is more reasonable to consider them as a measurement error rather than introduce a new independent variable into the model.

### UNREPLICATED LINEAR FUNCTIONAL RELATIONSHIP MODEL

Suppose that X and Y are two linearly related unobservable variables

$$Y_i = a + \beta X_i \quad (1)$$

and the two corresponding random variables x and y are observed with error  $\delta$  and  $\epsilon$ , respectively as

$$\left. \begin{aligned} x_i &= X_i + \delta_i \\ y_i &= Y_i + \epsilon_i \end{aligned} \right\} \quad i = 1, 2, \dots, n \quad (2)$$

The following conditions are assumed

$$\left. \begin{aligned} E(\delta_i) &= E(\epsilon_i) = 0, \quad \text{Var}(\delta_i) = \sigma_\delta^2, \quad \text{Var}(\epsilon_i) = \sigma_\epsilon^2, \quad \forall i \\ \text{Cov}(\delta_i, \delta_j) &= \text{Cov}(\epsilon_i, \epsilon_j) = 0, \quad i \neq j \\ \text{Cov}(\delta_i, \epsilon_j) &= 0, \quad \forall i, j \end{aligned} \right\} \quad (3)$$

where,  $\delta_i$  and  $\epsilon_i$  are mutually independent and normally distributed random variables. Equation 1 and 2 are known as ULFR model when there is only one relationship between the two variables X and Y. When the ratio of the error variances is known, that is  $\sigma_\delta^2 / \sigma_\epsilon^2 = \lambda$ , then the maximum likelihood estimators of parameters  $\alpha$ ,  $\beta$ ,  $\sigma_\delta^2$  and  $X_i$  are:

$$\hat{\alpha} = \bar{y} - \hat{\beta}\bar{x} \quad (4)$$

$$\hat{\beta} = \frac{(S_{yy} - \lambda S_{xx}) + \left\{ (S_{yy} - \lambda S_{xx})^2 + 4\lambda S_{xy}^2 \right\}^{1/2}}{2S_{xy}} \quad (5)$$

$$\hat{\sigma}_\delta^2 = \frac{1}{n-2} \left[ \sum (x_i - \hat{X}_i)^2 + \frac{1}{\lambda} \sum (y_i - \hat{\alpha} - \hat{\beta}\hat{X}_i)^2 \right] \quad (6)$$

and

$$\hat{X}_i = \frac{\lambda x_i + \hat{\beta}(y_i - \hat{\alpha})}{\lambda + \hat{\beta}^2} \quad (7)$$

where,

$$\bar{y} = \frac{\sum y_i}{n}, \bar{x} = \frac{\sum x_i}{n}$$

$$S_{yy} = \sum (y_i - \bar{y})^2, S_{xx} = \sum (x_i - \bar{x})^2 \text{ and}$$

$$S_{xy} = \sum (x_i - \bar{x})(y_i - \bar{y})$$

**DERIVATION OF THE COEFFICIENT OF DETERMINATION (COD)**

In an ordinary SL regression analysis, we look at the COD as a measure of the variability in y explained by the regression model. The construction of the COD is a good practice when fitting the ULFR model.

The Eq. 1 and 2 can be rewritten as

$$y_i = \alpha + \beta X_i + \varepsilon_i \text{ for } i = 1, 2, \dots, n \quad (8)$$

If we substitute  $X_i$  by  $(x_i - \delta_i)$  in (8), then we have the expression

$$y_i = \alpha + \beta x_i + (\varepsilon_i - \beta \delta_i)$$

$$= \alpha + \beta x_i + V_i$$

Where, the errors of the model  $V_i = (\varepsilon_i - \beta \delta_i) = y_i - (\alpha + \beta x_i)$ , for  $i = 1, 2, \dots, n$  is a normally distributed random variable with zero mean and variance  $\sigma_\varepsilon^2 + \beta^2 \sigma_\delta^2$ . If  $\hat{\alpha}$  and  $\hat{\beta}$  are the estimates of  $\alpha$  and  $\beta$  respectively, then

$$\hat{V}_i = y_i - \hat{y}_i = y_i - (\hat{\alpha} + \hat{\beta} x_i), \text{ for } i = 1, 2, \dots, n \quad (9)$$

will be the residual of the model. From Kendall and Stuart (1979) and Anderson (1984), that the sum of squared distances of the observed points from the fitted line or the residual sum of squares ( $SS_E$ ) is given as:

$$SS_E = \frac{\sum \left\{ y_i - \left( \hat{\alpha} + \hat{\beta} x_i \right) \right\}^2}{\left( \lambda + \hat{\beta}^2 \right)} = \frac{S_{yy} - 2\hat{\beta}S_{xy} + \hat{\beta}^2 S_{xx}}{\left( \lambda + \hat{\beta}^2 \right)} \quad (10)$$

We shall consider here that the ratio of the error variances is equal to one ( $\lambda = 1$ ). For those cases when  $\lambda \neq 1$ , we can always reduce this to the case of  $\lambda = 1$  by dividing the observed values of y by  $\lambda^{1/2}$  (Kendall and Stuart, 1979). Hence, we have:

$$SS_E = \frac{S_{yy} - 2\hat{\beta}S_{xy} + \hat{\beta}^2 S_{xx}}{1 + \hat{\beta}^2} \quad (11)$$

In the same way as ordinary linear regression, we can now define the COD of the ULFR ( $R_F^2$ ) as the proportion of variation explained by the variable x, that is:

$$R_F^2 = \frac{SS_R}{S_{yy}} \quad (12)$$

where,  $SS_R$  is the regression sum of squares which can be derived as:

$$SS_R = S_{yy} - SS_E = S_{yy} - \frac{S_{yy} - 2\hat{\beta}S_{xy} + \hat{\beta}^2 S_{xx}}{1 + \hat{\beta}^2} \quad (13)$$

$$= \frac{\hat{\beta}^2 S_{yy} + 2\hat{\beta}S_{xy} - \hat{\beta}^2 S_{xx}}{1 + \hat{\beta}^2} = \frac{\hat{\beta}^2 (S_{yy} - S_{xx}) + 2\hat{\beta}S_{xy}}{1 + \hat{\beta}^2}$$

We can summarise our proposed COD with the following results.

**Result 1:** Let the ratio of the error variances be known and is equal to one,  $\sigma_\varepsilon^2/\sigma_\delta^2 = \lambda = 1$ , then the COD for the ULFR model is

$$R_F^2 = \frac{SS_R}{S_{yy}} = \frac{\hat{\beta}S_{xy}}{S_{yy}} \quad (14)$$

**Proof:** When  $\lambda = 1$ , then  $\hat{\beta}$  in Eq. 5 becomes

$$\hat{\beta} = \frac{(S_{yy} - S_{xx}) + \left[ (S_{yy} - S_{xx})^2 + 4S_{xy}^2 \right]^{1/2}}{2S_{xy}}$$

$$\text{and } \hat{\beta}^2 = \frac{(S_{yy} - S_{xx})\hat{\beta} + S_{xy}}{S_{xy}}$$

Notice that  $\frac{SS_R}{S_{yy}} = \frac{\hat{\beta}S_{xy}}{S_{yy}} \Leftrightarrow SS_R = \hat{\beta}S_{xy}$  From Eq. 13,

we have,

$$\begin{aligned} \frac{\hat{\beta}^2 (S_{yy} - S_{xx}) + 2\hat{\beta}S_{xy}}{1 + \hat{\beta}^2} &= \hat{\beta}S_{xy} \\ \Leftrightarrow \hat{\beta}^2 (S_{yy} - S_{xx}) &= \hat{\beta}^3 S_{xy} - \hat{\beta}S_{xy} \\ \Leftrightarrow \hat{\beta}(S_{yy} - S_{xx}) &= (\hat{\beta}^2 - 1)S_{xy} \end{aligned}$$

From the R.H.S.

$$\begin{aligned} (\hat{\beta}^2 - 1)S_{xy} &= \left[ \frac{(S_{yy} - S_{xx})\hat{\beta} + S_{xy}}{S_{xy}} - 1 \right] S_{xy} \\ &= \left[ \frac{(S_{yy} - S_{xx})\hat{\beta} + S_{xy} - S_{xy}}{S_{xy}} \right] S_{xy} \\ &= \hat{\beta}(S_{yy} - S_{xx}) \end{aligned}$$

**Result 2:** Let  $\hat{\beta}_s$  and  $\hat{\beta}$  be the slope estimator for the simple linear regression and the ULFR, respectively. The corresponding COD are:

$$R_s^2 = \frac{\hat{\beta}_s^2 S_{xy}}{S_{yy}} \quad \text{and} \quad R_F^2 = \frac{\hat{\beta}^2 S_{xy}}{S_{yy}} \quad (\text{when } l = 1)$$

Then  $0 \leq R_s^2 \leq R_F^2 \leq 1$ .

**Proof:** From the regression sum of squares, we obtain

$$\begin{aligned} 0 \leq SS_R &= S_{yy} - SS_E \leq S_{yy} \\ 0 \leq R_F^2 &= \frac{SS_R}{S_{yy}} \leq 1 \end{aligned}$$

we also know that simple linear regression has  $0 \leq R_s^2 \leq 1$ . We now proof  $R_s^2 \leq R_F^2$  by contradiction. Assuming that

$$R_s^2 = \frac{S_{xy}^2}{S_{xx}S_{yy}} > \frac{\left\{ (S_{yy} - S_{xx}) + \sqrt{(S_{yy} - S_{xx})^2 + 4S_{xy}^2} \right\} S_{xy}}{2S_{xy}S_{yy}} = R_F^2$$

$$\frac{2S_{xy}^2}{S_{xx}} - (S_{yy} - S_{xx}) > \sqrt{(S_{yy} - S_{xx})^2 + 4S_{xy}^2}$$

$$\begin{aligned} \frac{4S_{xy}^4}{S_{xx}^2} + (S_{yy} - S_{xx})^2 - \frac{4S_{xy}^2(S_{yy} - S_{xx})}{S_{xx}} &> (S_{yy} - S_{xx})^2 + 4S_{xy}^2 \\ S_{xy}^4 - S_{xy}^2 S_{xx} (S_{yy} - S_{xx}) &> S_{xy}^2 S_{xx}^2 \\ S_{xy}^4 &> S_{xy}^2 S_{xx} (S_{xx} + S_{yy} - S_{xx}) \\ S_{xy}^2 &> S_{xx} S_{yy} \end{aligned}$$

Also from  $R_s^2 = S_{xy}^2 / S_{xx}S_{yy} < 1 \Rightarrow S_{xy}^2 < S_{xx}S_{yy}$ , this is a contradiction. Hence, we have  $R_s^2 \leq R_F^2$ .

### PROPERTIES OF $R_F^2$

Since  $R_F^2$  is computed following the same method as  $R_s^2$ , some of the properties of  $R_s^2$  may also remain for  $R_F^2$ . It is known that  $R_s^2$  does not measure the appropriateness of the linear model (Montgomery and Peck, 1992). This holds for  $R_F^2$  too. As an example, when a nonlinear model has a large  $R_s^2$  value, it is obvious that  $R_F^2$  will also be large (Result 2).

Secondly, the magnitude of  $R_F^2$  depends on the range of variability in the variables X and Y. From Eq. 14, we have

$$\begin{aligned} R_F^2 &= \frac{\hat{\beta}^2 S_{xy}}{S_{yy}} \\ &= \frac{\left\{ (S_{yy} - S_{xx}) + \sqrt{(S_{yy} - S_{xx})^2 + 4S_{xy}^2} \right\} S_{xy}}{2S_{xy}S_{yy}} \\ &= \frac{\left\{ (S_{yy} - S_{xx}) + \sqrt{(S_{yy} - S_{xx})^2 + 4S_{xy}^2} \right\}}{2S_{yy}} \end{aligned}$$

Let  $\text{var}(X)$  and  $\text{var}(Y)$  be variances of X and Y, respectively then  $\text{var}(X) = S_{xx} / n - 1$  and  $\text{var}(Y) = S_{yy} / n - 1$ . We consider three possible cases of relationship between  $\text{var}(X)$  and  $\text{var}(Y)$  when  $S_{xx} > 0$  and  $S_{yy} > 0$ .

**Case 1:** If  $\text{var}(X) = \text{var}(Y) \Leftrightarrow S_{xx} = S_{yy}$ , then

$$R_F^2 = \frac{\sqrt{4S_{xy}^2}}{2S_{yy}} = \frac{2S_{xy}}{2S_{yy}} = \frac{S_{xy}}{S_{yy}}$$

when compared with Eq. 14, this holds when  $\hat{\beta} = 1$ .

**Case 2:** If  $\text{var}(X) < \text{var}(Y) \Leftrightarrow S_{yy}/k = S_{xx} < S_{yy}$  for  $k > 1$ , then

$$\begin{aligned} R_F^2 &= \frac{\left( S_{yy} - \frac{S_{xy}}{k} \right) + \sqrt{\left( S_{yy} - \frac{S_{xy}}{k} \right)^2 + 4S_{xy}^2}}{2S_{yy}} \\ &= \frac{\frac{(k-1)}{k} S_{yy} + \sqrt{\frac{(k-1)^2}{k^2} S_{yy}^2 + 4S_{xy}^2}}{2S_{yy}} \\ &> \frac{\frac{(k-1)}{k} S_{yy} + \sqrt{4S_{xy}^2}}{2S_{yy}} = \frac{(k-1)}{2k} + \frac{S_{xy}}{S_{yy}} > \frac{S_{xy}}{S_{yy}} \end{aligned}$$

when compared with Eq. 14, this holds when  $\hat{\beta} > 1$ .

**Case 3:** If  $\text{var}(X) > \text{var}(Y) \Leftrightarrow kS_{yy} = S_{xx}$  for  $k > 1$ , then

$$\begin{aligned} R_F^2 &= \frac{-(kS_{yy} - S_{yy}) + \sqrt{(S_{yy} - kS_{yy})^2 + 4S_{xy}^2}}{2S_{yy}} \\ &= \frac{-(k-1)S_{yy} + \sqrt{(1-k)^2 S_{yy}^2 + 4S_{xy}^2}}{2S_{yy}} \\ &< \sqrt{\frac{(1-k)^2 S_{yy}^2 + 4S_{xy}^2}{4S_{yy}^2}} \\ &= \sqrt{\frac{(1-k)^2}{4} + \frac{S_{xy}^2}{S_{yy}^2}} < \frac{(1-k)}{2} + \frac{S_{xy}}{S_{yy}} < \frac{S_{xy}}{S_{yy}} \end{aligned}$$

when compared with Eq. 14, this holds when  $\hat{\beta} < 1$ .

We can summarize the above properties with the following result.

**Result 3:** Let  $S_{xx} > 0$ ,  $S_{yy} > 0$  and  $S_{xx} = kS_{yy}$  or  $\text{var}(x) = k \text{var}(y)$ , then

- a)  $R_F^2 > \frac{S_{xy}}{S_{yy}} \Leftrightarrow \hat{\beta} > 1, \quad 0 < k < 1$
- b)  $R_F^2 = \frac{S_{xy}}{S_{yy}} \Leftrightarrow \hat{\beta} = 1, \quad k = 1$
- c)  $R_F^2 < \frac{S_{xy}}{S_{yy}} \Leftrightarrow \hat{\beta} < 1, \quad k > 1.$

The numerical example of the above results is given in Fig. 1a-1f. To explain the relationship between  $R_F^2$  and

$R_S^2$ , the value of CODs are compared for different sample sizes ( $n = 10, 50, 100, 1000, 5000$  and  $10000$ ). For a given sample size, fifty samples were generated from a uniform distribution, each contains two random data sets ( $y_i, x_i$ ). As an example, Fig. 1a shows fifty values of COD derived from SL and ULFR methods with sample size  $n = 10$ . Figure 1b-1f show the same plot with sample sizes  $n = 50, 100, 1000, 5000$  and  $10000$ , respectively. It is clearly shown that  $R_F^2$  is always greater or equal to  $R_S^2$ . One interesting feature shown in Fig. 1 is that both  $R_F^2$  and  $R_S^2$  decreased when the sample size increased.

### APPLICATION IN ROAD ACCIDENT PROBLEM

So far, various road accident models have been proposed to explain Malaysian road accident phenomena (Radin *et al.*, 1995; Radin, 1996; Razali and Dahalan, 1992). However, PDRM road statistics show that the number of road accidents still remains high. One reason the Malaysian road accident problem has not been solved effectively is that the existing models are constructed for prediction purpose rather than causal inference. The crucial factor ignored in the existing models is the driver's state of mind that cannot be measured directly. The driver state of mind includes driver's attitude, ability to concentrate and tendency to take risks. It has been suggested that the driver's state of mind is an essential factor that causes road accident (Leeming, 1969; Forbes, 1972).

In this example, we introduce the state of mind as a factor that causes variations in other physically measurable factors such as driver's sex, age and race. This is formally expressed using the ULFR model where the measurement error,  $\delta$  is representing the state of mind. Difference between  $R_F^2$  and  $R_S^2$  is used to measure the effect of the state of mind to the road accident model. Since  $R_F^2$  and  $R_S^2$  have similar interpretations by construction, when  $R_F^2$  is significantly larger than  $R_S^2$  we say that the state of mind has been incorporated into the independent variable and the model now explains the causal relationship of road accident.

Table 1 shows the socio-biological variables of the Malaysian road accident data for 1996 obtained from Malaysian Royal Police (PDRM) headquarters. The Box-Cox power transformation (Box and Cox, 1964) is presented to access normality with  $[\lambda_Y \ \lambda_{R_1} \ \dots \ \lambda_{P_5}] = [0.25 \ 0.69 \ 1.25 \ 0.14 \ 0.23 \ 0.47]$ . Without loss of generality, we assume that the ratio of variances,  $\lambda$ , equals one by dividing the number of state accidents by the total number of accidents in Malaysia.

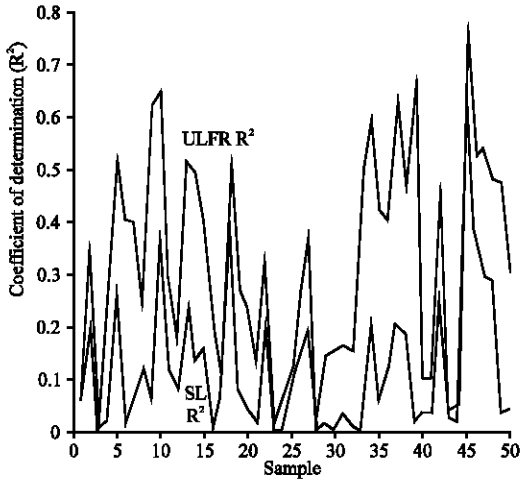


Fig. 1a: COD plots for SL and ULFR models with  $n = 10$

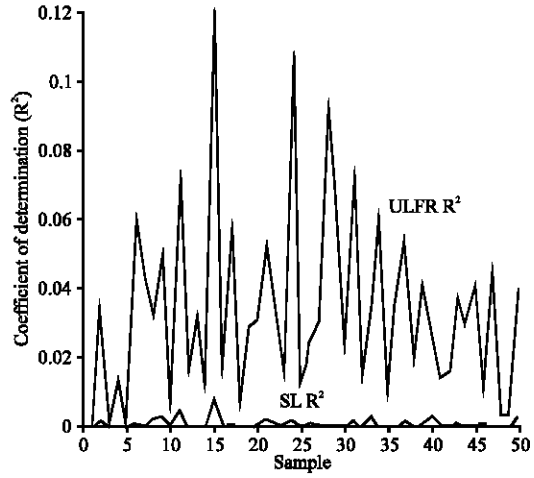


Fig. 1d: COD plot for SL and ULFR models with  $n = 1000$

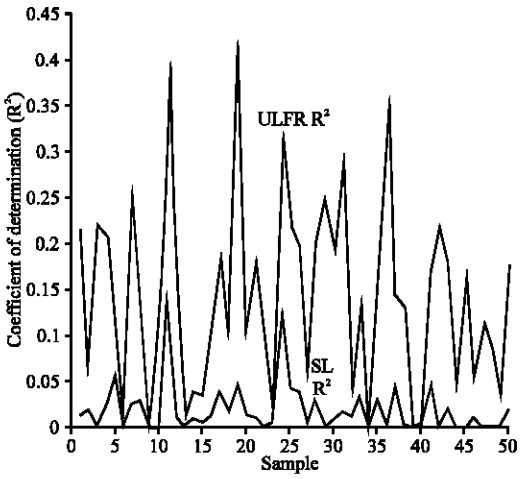


Fig. 1b: COD plot for SL and ULFR models with  $n = 50$

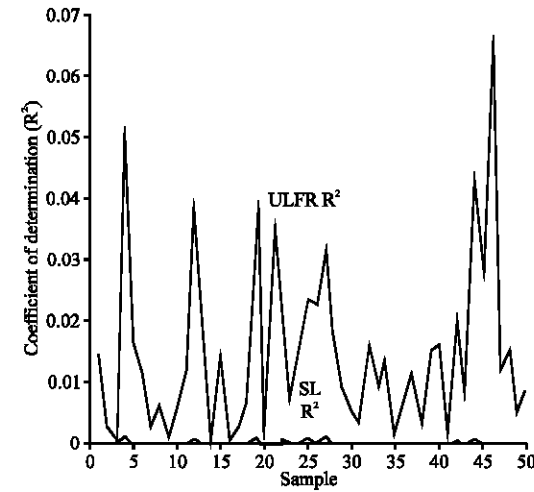


Fig. 1e: COD plots for SL and ULFR models with  $n = 5000$

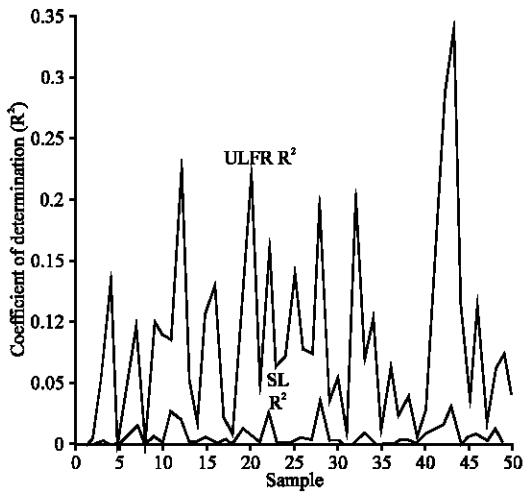


Fig. 1c: COD plots for SL and ULFR models with  $n = 100$

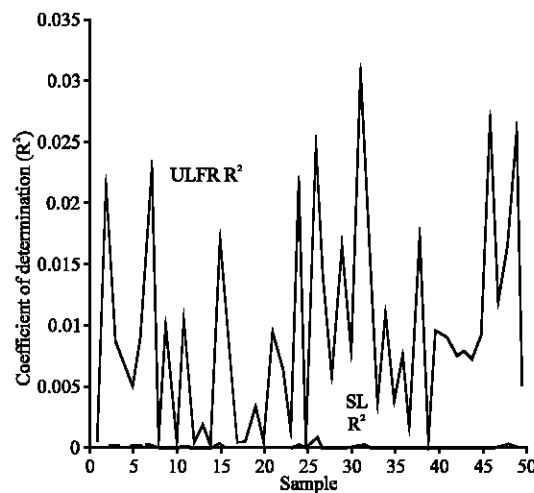


Fig. 1f: COD plot for SL and ULFR models with  $n = 10000$

Table 1: Socio-biological explanatory variables

State	Y	P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>	P <sub>5</sub>
Perlis	0.208	0.4856	0.1491	0.02	0.4741	0.9051
Kedah	1.410	0.4686	0.2282	0.04	0.3965	0.9072
Perak	1.921	0.4670	0.3338	0.06	0.4440	0.9126
Penang	1.277	0.5600	0.3923	0.08	0.5542	0.9173
K.Lumpur	1.597	0.5401	0.3791	0.16	0.6119	0.9590
Selangor	2.208	0.5428	0.2800	0.09	0.4596	0.9401
N.Sembilan	1.121	0.5070	0.2638	0.04	0.5061	0.9385
Malacca	1.008	0.5342	0.3215	0.08	0.3386	0.9302
Johore	2.451	0.5173	0.3545	0.11	0.4363	0.9371
Pahang	0.971	0.5086	0.2196	0.02	0.3436	0.9496
Terengganu	0.716	0.4955	0.0554	0.01	0.4559	0.9278
Kelantan	0.934	0.4577	0.0880	0.07	0.3688	0.9203
Sabah	0.469	0.4479	0.2353	0.05	0.4128	0.9505
Sarawak	0.552	0.5122	0.4206	0.11	0.4452	0.9121

Source: PDRM (Malaysian Royal Police, 1995-1998)

**Note:**

- The number of vehicles involved in 1996 does not include accident of type ‘slightly injured’ and property damaged only
- Y = number of road accidents (‘000)  
 P<sub>1</sub> = Age (ratio of drivers aged 16-30 years to total number of drivers involved in accidents)  
 P<sub>2</sub> = Race (ratio of Chinese drivers to total number of drivers involved in accidents)  
 P<sub>3</sub> = Number of serious and fatal accidents due to influence of alcohol (‘00)  
 P<sub>4</sub> = Experience (ratio of vehicles with drivers of less than 5 years’ experience to total number of vehicles involved in accidents)  
 P<sub>5</sub> = Sex (ratio of male drivers to total number of drivers involved in accidents)
- The numbers given are ratios explained in (2). For example, 0.28 in column two row six means that for every 100 cases of road accident in Selangor during 1996 about 28 cases involved Chinese drivers.

First, we look at the estimation of parameters for the ULFR model containing the state of mind measurement error for drivers age (P<sub>1</sub>) is given as

$$S_{yy} = 0.0199 \quad S_{P_1Y} = 0.0154 \quad S_{P_1P_1} = 0.0062$$

$$\hat{\beta} = \frac{(0.0199 - 0.0154) + \left[ \frac{(0.0199 - 0.0154)^2 + 4(0.0062)^2}{2(0.0062)} \right]^{1/2}}{2(0.0062)} = 1.4264$$

$$\hat{\alpha} = 0.0714 - 1.4264(0.5032) = -0.6463$$

therefore, the ULFR model is

Table 2: Estimated parameters, coefficient of determination for the ULFR and SL models and the effect of measurement error

Variables	$\hat{\alpha}$	$\hat{\beta}$	R <sub>F</sub> <sup>2</sup>	$\hat{\alpha}_s$	$\hat{\beta}_s$	R <sub>S</sub> <sup>2</sup>	E <sub>e</sub>
P <sub>1</sub>	-0.6463	1.4264	0.4408	-0.1290	0.3983	0.1231	0.3177
P <sub>2</sub>	0.0275	0.1652	0.2010	0.0318	0.1490	0.1814	0.0196
P <sub>3</sub>	0.0164	0.7698	0.4215	0.0411	0.4245	0.2324	0.1891
P <sub>4</sub>	0.0171	0.1218	0.0421	0.0308	0.0911	0.0315	0.0106
P <sub>5</sub>	-7.8582	8.5348	0.8162	-0.3842	0.4904	0.0469	0.7693

$$\hat{Y} = -0.6463 + 1.4264 P_1$$

with the coefficient of determination, R<sub>F</sub><sup>2</sup> = 0.4408

$\left( \frac{S_{xy}}{S_{yy}} = 0.3116 \text{ and } \hat{\beta} > 1 \right)$  (see Result 3). Comparing with

the SL model

$$\hat{Y} = -0.1290 + 0.3983 P_1 \quad \text{and} \quad R_s^2 = 0.1231$$

the result shows that the ULFR model explains the variability of Y better than the SL model (R<sub>F</sub><sup>2</sup> > R<sub>S</sub><sup>2</sup>). The SL model explains 12.31% of the variance of the number of road accidents but it increases to 44.08% when conditioned to ‘state of mind’ factor. This suggests that the state of mind explains 31.77% (E<sub>e</sub> = R<sub>F</sub><sup>2</sup> - R<sub>S</sub><sup>2</sup>) of the variance of road accident number.

It is clearly show (Table 2) that the ULFR model gives a better fit than the SL model with higher COD. The SL model indicates that variables P<sub>1</sub>, P<sub>3</sub> and P<sub>5</sub> are not significantly contribute to the road accident rates. The first interpretation opposes other studies (Arthur and Little, 1970; IATSS, 1988; OECD Road Research Group, 1978; OECD Scientific Export Group, 1986) that age, gentle and alcoholic are important factors. However, when the state of mind is introduced, the three variables, especially P<sub>5</sub> become important and it may use to explain causal relationship of the road accident. For example, we say the younger driver may be the cause of higher accident rates because of their driving attitude or tendency to take risks.

The introduction of state of mind does not increase the COD of variables P<sub>2</sub> and P<sub>4</sub> significantly. This suggests that the driver’s race and experience are two exact predictor of road accident. On the other hand, both R<sub>S</sub><sup>2</sup> and R<sub>F</sub><sup>2</sup> indicate race and driving experience are not significantly explained the road accident model. Henceforth, only variables P<sub>1</sub>, P<sub>3</sub> and P<sub>5</sub> are recommended for further analysis such as multiple regression.

**CONCLUSION AND FURTHER WORK**

In this study, the COD of ULFR is proposed and it properties are investigated. The proposed COD and the

COD of ordinary linear regression model are used to investigate the effect of measurement error and hence try to explain the causal relationship of the model. It is a useful way to check whether a variable is reasonably assumed to be independent. This study on the Malaysian road accident problem demonstrates that the effect of the state of mind, indicated by the measurement error is clear but different in all factors.

However, confirmation of the causal properties in the ULFR model may be further strengthening by studying further the distribution of  $R_F^2$ . The multivariate version of ULFR may also be considered in further studies.

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