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## Study of Horizontal Well Fracture Initiation Pressure Based on Nonlinear Constraint Model

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**Abstract:** Hydraulic fracturing of horizontal well has been a principal stimulation treatment for low permeable reservoirs. Accurately calculate Fracture Initiation Pressure (FIP) is a key factor to the success of hydraulic fracturing operation for horizontal well. Conventional FIP solution model of horizontal well utilize well-bore pressure increment as the iteration step. Therefore, it has disadvantages such as slow convergence speed and lower computational precision. In this paper, a new optimization solution model is proposed for horizontal well FIP calculation. The model transforms the solving process of FIP into the searching problem of minimum objective function under nonlinear constraint condition. Optimization calculation equations for FIP for horizontal well under open hole and perforation completion is established based on the model. The solving flow chart by using outer-point-penalty function method is devised. Verification of the model is completed through calculation of an actual horizontal well data. The results show that proposed model has superiority of faster computational convergence speed and higher calculation precision than the convention models.

**Key words:** Horizontal well, hydraulic fracturing, fracture initiation pressure, optimization theory, nonlinear constraint model

### INTRODUCTION

Accurately calculate Fracture Initiation Pressure (FIP) has been a key factor to the success of horizontal well hydraulic fracturing treatment. In general, the influence factors of FIP includes the in-situ stress magnitude and formation pressure, wellbore pressure and fracturing fluid percolation effect, reservoir temperature, formation rock strength and other rock mechanics properties (Tuman, 1962; Closmann and Phocas, 1978; Zhou 2002; Xu, 2004). At present, the FIP calculation is based on the total stress distribution around the horizontal well. While the tensile stress application to the rock of well bore exceeds the tensile strength, the rock burst and hydraulic fracture generated. Conventional FIP calculation model of horizontal well uses the well-bore pressure increment as iteration step and leads to the disadvantages such as slow convergence speed and lower precision. To improve the inadequateness, a new nonlinear constraint solution

model based on optimization theory for horizontal well hydraulic fracturing initiation pressure is proposed in this paper.

### STRESS FIELD DISTRIBUTION MODEL AROUND HORIZONTAL WELL

**Stress field distribution around open hole horizontal well:** Due to the horizontal wellbore axial length is far greater than radial diameter and therefore it is reasonable assumed that wellbore z axis strain is constant under fracturing conditions and that of x, y plane displacement is unrelated with the z axis, the stress distribution around the horizontal wellbore wall is defined as a plane strain problem (define compressive stress and fluid pressure is positive). Assumes that the rock surrounding the well-bore is homogeneous, isotropic and according to the linear elastic stress calculation model, the stress field distribution surrounding horizontal wellbore wall was

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derived (Risnes *et al.*, 1982; Hossain *et al.*, 1999; Russel *et al.*, 2009; Fallahzadeh *et al.*, 2010):

$$\begin{cases} \sigma_r = P_w \\ \sigma_\theta = -P_w + (\sigma_v + \sigma_h + \Delta\sigma \cos^2 \beta) - 2(\sigma_v - \sigma_h - \Delta\sigma \cos^2 \beta) \cos 2\theta \\ \sigma_z = \sigma_h + \Delta\sigma \sin^2 \beta - 2\nu (\sigma_v - \sigma_h - \Delta\sigma \cos^2 \beta) \cos 2\theta \\ \tau_{r\theta} = \tau_{rz} = 0 \\ \tau_{\theta z} = \Delta\sigma \sin 2\beta \cos \theta \end{cases} \quad (1)$$

In Eq. 1,  $\sigma_w$ ,  $\sigma_h$ ,  $\sigma_v$  = vertical principal stress, maximum horizontal principal stress, minimum horizontal principal stress, MPa,

$\sigma_r$ ,  $\sigma_\theta$ ,  $\sigma_z$  = horizontal wellbore wall radial stress, tangential stress, axial stress at angle  $\theta$  on the horizontal wellbore wall under cylindrical coordinate system, MPa;  $\tau_{r\theta}$ ,  $\tau_{rz}$ ,  $\tau_{\theta z}$  = horizontal wellbore wall shear stress on the horizontal wellbore wall under cylindrical coordinate system, Mpa;  $\Delta\sigma = \sigma_h - \sigma_v$  horizontal stress anisotropy, MPa;  $\beta$  = azimuth angle, horizontal wellbore anticlockwise turned angle w.r.t  $\sigma_h$ , degree;  $\theta$  = Initiation angle, horizontal wellbore anticlockwise turned angle w.r.t  $\sigma_v$ , degree;  $P_w$  = horizontal wellbore pressure, Mpa;  $\nu$  = Poisson's ratio of horizontal well-bore surrounding rock, dimensionless.

### Stress field distribution around perforation completion

**horizontal well:** Stress field distribution surrounding perforation completion horizontal wellbore wall is distinguish from the open hole completion, perforation tunnel and horizontal wellbore are two different size of the hole in the perpendicular intersection, by superposition of stress concentration in wellbore and perforation hole intersection, the stress distribution in junction of perforation and sidewall boundary was given:

$$\begin{cases} \sigma_r = P_w \\ \sigma_\theta = -2P_w (1 + \cos 2\theta) + 2[\sigma_v(1 + 2\nu \cos 2\theta) + 2\sigma_h \nu \cos 2\theta + \Delta\sigma(\cos^2 \beta(1 + 2\nu \cos 2\theta) - \sin^2 \beta)] \cos 2\theta - 2[\sigma_v - \sigma_h - \Delta\sigma \cos^2 \beta] \cos 2\theta(1 + \cos 2\theta) \\ \quad + [\sigma_v(1 - 2\nu \cos 2\theta) + \sigma_h(2 + 2\nu \cos 2\theta) + \Delta\sigma(1 + 2\nu \cos^2 \beta \cos 2\theta)] \\ \sigma_z = \sigma_h + \Delta\sigma \sin^2 \beta - 2\nu(\sigma_v - \sigma_h - \Delta\sigma \cos^2 \beta) \cos 2\theta \\ \tau_{r\theta} = \tau_{rz} = 0 \\ \tau_{\theta z} = \Delta\sigma \sin 2\beta \cos \theta \end{cases} \quad (2)$$

In Eq. 2,  $\theta$  = perforation azimuth angle, anticlockwise turned angle w.r.t  $\sigma_v$ , degree,

$\theta'$  = horizontal wellbore anticlockwise turned angle w.r.t  $\sigma_v$ , degree,

$\sigma_\theta$  = tangential stress in wellbore and perforation hole intersection, MPa.

Fracture initiation criterion: According to tensile strength criterion, when any of the principal stress on

wellbore wall exceeds the tensile strength of the rock, then the fracture initiates. Due to the radial stress  $\sigma_r$  is one of the principal stresses, so other two principal stresses can be calculated by using the theory of combined stresses, thus the expression is:

$$\begin{cases} \sigma_1 = \sigma_r \\ \sigma_2 = \frac{1}{2}[(\sigma_\theta + \sigma_z) + \sqrt{(\sigma_\theta - \sigma_z)^2 + 4\tau_{\theta z}^2}] \\ \sigma_3 = \frac{1}{2}[(\sigma_\theta + \sigma_z) - \sqrt{(\sigma_\theta - \sigma_z)^2 + 4\tau_{\theta z}^2}] \end{cases} \quad (3)$$

In Eq. 3, Initiation pressure calculation of perforation completion, substitute as  $\sigma_\theta$  as  $\sigma_\theta$ .

From Eq. 3 it is clear that  $\sigma_2$  is maximum tensile stress of horizontal wellbore wall, considering the effect of pore pressure, the fracture may crack when the stress of the wellbore wall satisfies the following condition, the corresponding  $P_w$  is initiation pressure,  $\theta$  (or  $\theta'$  perforation well) for fracture azimuth,

$$\sigma_2 - P_p = \sigma_t \quad (4)$$

where,  $P_p$  is pore pressure, MPa;  $\sigma_t$  is rock tensile strength, MPa.

### NONLINEAR CONSTRAINTS NUMERICAL MODEL FOR FIP

Because of the maximum stress  $\sigma_2$  is associated with wellbore pressure  $P_w$ , the conventional calculation method assume  $P_w$  increase from the minimum value, until satisfies the formula above, the final wellbore pressure solving by Eq. 4 named  $P_{wf}$  is the FIP and corresponding  $\theta_f$  (or  $\theta'_f$  for perforation well) is the fracture initiation azimuth. Conventional solving process requires iteration calculation, solving speed is slow and the solving precision depends on increment of wellbore pressure  $P_w$ . Based on optimization theory, nonlinear constraints numerical model of FIP for open hole and perforating horizontal well is established, respectively.

Numerical model for open hole horizontal well: In solving process for FIP by using Eq. 4,  $P_w$  and  $\theta$  are unknown parameters, for the purposes of generating nonlinear constrained numerical model, following definition is made at first:

$$\begin{aligned} x_1 &= \cos \theta, x_2 = \sin \theta, x_3 = \sigma_\theta, A = \sigma_v + \sigma_h + \Delta\sigma \cos^2 \beta, B = \sigma_v - \sigma_h - \Delta\sigma \cos^2 \beta, \\ C &= \sigma_h + \Delta\sigma \sin^2 \beta, D = P_p + \sigma_t, E = \Delta\sigma \sin 2\beta \end{aligned} \quad (5)$$

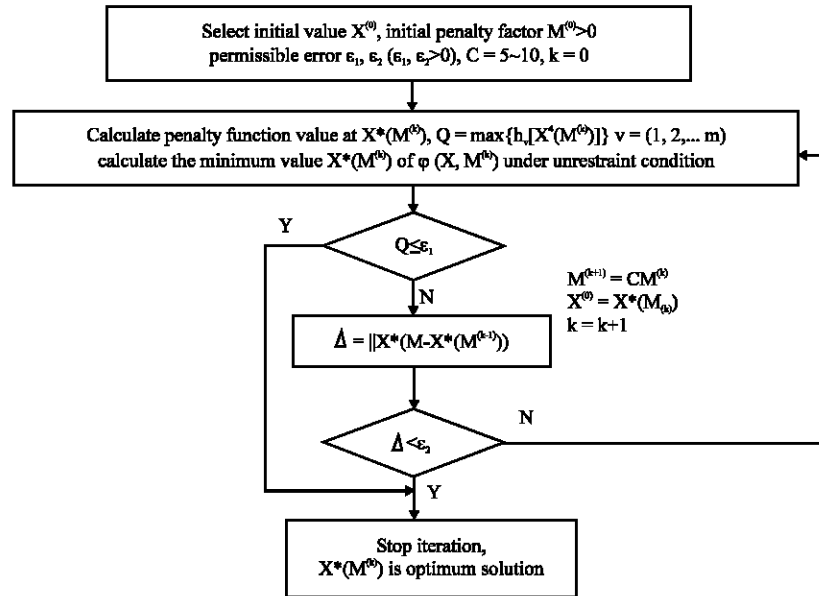


Fig. 1: FIP solving flowchart by using outer point penalty function method

Then the optimization equation can be written as follows:

$$\begin{cases} \min P_w = f(x_1, x_2, x_3) = A - 2B(x_1^2 - x_2^2) - x_3 \\ \text{s.t. } \sigma_z = C - 2vB(x_1^2 - x_2^2) \\ E^2 x_1^2 - D^2 + (D - \sigma_z)x_3 + D\sigma_z = 0 \\ x_1^2 + x_2^2 = 1 \end{cases} \quad (6)$$

Numerical model for perforation horizontal well: For fracture initiation calculation of perforation completion horizontal well, the unknown parameters are  $P_w$  and  $\theta'$ , in order to establish the optimization equation, following definition is made at first:

$$\begin{aligned} x_1 &= \cos 2\theta', x_2 = \sigma_\theta, \\ A &= [\sigma_v(1 + 2v \cos 2\theta) + 2\sigma_h v \cos 2\theta + \Delta\sigma(\cos^2 \beta(1 + 2v \cos 2\theta) - \sin^2 \beta)], \\ B &= [\sigma_v - \sigma_h - \Delta\sigma \cos^2 \beta] \cos 2\theta, \\ C &= [\sigma_v(1 - 2v \cos 2\theta) + \sigma_h(2 + 2v \cos 2\theta) + \Delta\sigma(1 + 2v \cos^2 \beta \cos 2\theta)], \\ D &= P_p + \sigma_1, E = \Delta\sigma \sin 2\beta \cos \theta, F = \sigma_h + \Delta\sigma \sin^2 \beta, \end{aligned} \quad (7)$$

Then the optimization equation can be written as follows:

$$\begin{cases} \min P_w = f(x_1, x_2) = (2 + 2x_1)^{-1}(2Ax_1 - x_2 - 2B(1 + x_1) + C) \\ \text{s.t. } \sigma_z = F - 2vB \\ \tau_{\theta z} = E \\ E^2 - D^2 + D(\sigma_z + x_2) - \sigma_z x_2 = 0 \\ -1 \leq x_1 \leq 1 \end{cases} \quad (8)$$

#### Computational flowchart of nonlinear constraint model:

The optimization calculation model (6), (8) is minimum value solving problem under the equality constraint condition, it is available to use the external penalty function method solving the solution (Chen and Zhao, 2002, 2011; Huang, 2009; Liu and Shan, 2011), the basic idea is, by constructing penalty function, convert the constraint problem into a series of unconstrained optimization problems, then using unconstrained optimization method to calculate, the fracture initiation calculation model of outer penalty function form to see Eq. 9, the calculation process is shown in Fig. 1:

$$\begin{cases} \min f(x_1, x_2, x_3) \\ \text{s.t. } h_v(x^*) = 0 \end{cases} \quad (9)$$

$$\varphi(X, M^{(k)}) = f(X) + M^{(k)} \sum [h_v(X)]^2$$

where,  $M^{(k)}$  is penalty factor, a set of ascending value greater than zero, must satisfies the condition of Eq. 10:

$$0 < M^{(0)} < M^{(1)} < \dots < M^{(k)} < M^{(k+1)} < \dots \rightarrow \infty \quad (10)$$

#### CALCULATION RESULT COMPARISON

Given an open hole completion horizontal well DP1 in Changqing oilfield to verify the new model, the basic parameters of DP1 as shown in Table 1:

According to the parameters in Table 1, the initial parameters to calculation are setting as follows, for new

**Table 1: Basic parameters of DP1 well for fracture initiation calculation**

| Mechanical parameter                         |       |                             |     |
|----------------------------------------------|-------|-----------------------------|-----|
| Vertical stress (MPa)                        | 40    | Horizontal max stress (MPa) | 45  |
| Pore pressure (MPa)                          | 20    | Horizontal min stress (MPa) | 30  |
| Rock mechanics parameter                     |       |                             |     |
| Young's modulus (MPa)                        | 10000 | Poisson ratio               | 0.3 |
| Horizontal wellbore parameter                |       |                             |     |
| Inclination angle of horizontal well(degree) | 90    |                             |     |
| Azimuth angle of horizontal well(degree)     | 30    |                             |     |

**Table 2: Comparison of computation results of DP1**

|                             | Result comparison |                    |                |                |
|-----------------------------|-------------------|--------------------|----------------|----------------|
|                             | New model         | Conventional model | Absolute error | Relative error |
| FIP (MPa)                   | 61.35             | 62.00              | 0.65           | 1.05%          |
| Initiation azimuth (degree) | 0.00              | 0.00               | 0.00           | 0.00           |
| Loop                        | 32.00             | 1500.00            | 1200.00        | 80.00%         |

model set  $[x_1, x_2, x_3] = [1, 0, 0]^T$ , for convention model set  $[P_w, \theta] = [0, 0]^T$  and  $[\Delta P_w, \Delta \theta] = [1, 15]^T$ . The calculated results by using new model and conventional model are shown in Table 2, respectively.

According to the contrast of computational results in Table 2, the conventional FIP calculation precision depends on the wellbore pressure increment, the convergence speed is slow and precision is low, while using the new optimization model to calculate, the results of FIP precision increase 1.05% and saving 80% convergence speed. It is shown that the new model is more applicable than the conventional one.

## CONCLUSION

This study has presented a nonlinear constraint model for calculation of hydraulic FIP for open hole or perforation completion horizontal well. The numerical model is based on the optimization theory and the solving flowchart is put forward in the paper by using outer point penalty function method. The comparison of FIP shows that the proposed optimization model has faster calculation convergence speed and higher calculation accuracy than the conventional one. Through application of computer technology to solve the proposed optimization model in the paper can provide a fast and high precision calculation method, it is better able to satisfy the site hydraulic fracture treatment requirements.

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